

MORPHOLOGICAL SEGMENTATION USING DIRICHLET PROCESS BASED
BAYESIAN NON-PARAMETRIC MODELS

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BASED BAYESIAN NON-PARAMETRIC MODELS**

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ABSTRACT

MORPHOLOGICAL SEGMENTATION USING DIRICHLET PROCESS BASED BAYESIAN NON-PARAMETRIC MODELS

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This study, will try to explore models explaining distributional properties of morphology within the morphological segmentation task. There are different learning approaches to the morphological segmentation task based on supervised, semi-supervised and unsupervised learning. The existing systems and how well semi-supervised and unsupervised non-parametric Bayesian models fit to the segmentation task will be investigated. Furthermore, the role of occurrence independent and co-occurrence based models in morpheme segmentation will be investigated.

Keywords: Natural Language Processing, Morphological Segmentation, Computational Linguistics, Dirichlet Process, Bayesian Non-Parametric Methods

ÖZ

DİRİCHLET SÜRECİ TEMELLİ PARAMETRİK OLMAYAN BAYES MODELLERİ İLE MORFOLOJİK BÖLÜMLEME

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Bu tezde, morfolojik bölümlenme içerisindeki dağılım özelliklerini açıklayan modeller incelenecektir. Morfolojik bölümlenmeye, gözetimli, yarı gözetimli ve gözetimsiz öğrenmeyi temel alan çeşitli öğrenim yaklaşımları mevcuttur. Bu çalışmada, mevcut sistemleri inceleyerek, parametrik olmayan yarı gözetimli ve gözetimsiz Bayes'ci yaklaşımların bölümlenme işlemine ne kadar uygun olduğunu gözlemleyeceğiz. Ek olarak, morfolojik bölümlenmede, morfolojileri birbirinden bağımsız ve bağımlı olarak ele alan modellerin rolleri incelenecektir.

Anahtar Kelimeler: Doğal Dil işleme, Morfolojik Bölümlenme, Hesaplamalı Dilbilim, Dirichlet Süreci, Parametrik Olmayan Bayes Modelleri

I dedicate my thesis to whom I love and many friends. My mother Tayyibe Yontar always supported me in my decisions and never gave up on me. My sister Sevcan Kumyol Yücel made me feel safe and confident during my entire study. The my beloved one Ece Oğur was my candle in the night that enlightened my path. I should also mention about my gratitude to my aunt Sema Kumyol Ridpath who supported me during my entire education.

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LIST OF ABBREVIATIONS

1	First Person
ACC	Accusative
ART	Article
AI	Artificial Intelligence
BTP	Backward Transitional Probability
CCG	Combinatory Categorical Grammar
CRP	Chinese Restaurant Process
DEM	Demonstrative
DP	Dirichlet Process
FTP	Frontward Transitional Probability
HDP	Hierarchical Dirichlet Process
HMM	Hidden Markov Model
HTP	High Transitional Probability
INST	Instrumental
LA	Language Acquisition
LOC	Locative
LOTH	Language of Thought
LSV	Letter Successor Variety
LTP	Low Transitional Probability
MAP	Maximum a Posteriori
MCMC	Markov Chain Monte Carlo
MDL	Minimum Description Length
ML	Maximum Likelihood
MLE	Maximum Likelihood Estimation
N	Noun
NLP	Natural Language Processing
OBJ	Object
PAS	Predicate-Argument Structure
PAST	Past tense
PCFG	Probabilistic Context-free Grammar
PLU	Plural
PMF	Probability Mass Function

POS	Poverty of Stimulus
POSS	Possessive
PRE	Prefix
SBJ	Subject
SF	Shannon-Fano Method
Sing	Singular
SV	Successor Variety
UG	Universal Grammar

CHAPTER 1

INTRODUCTION

1.1 Introduction

The term **morphology** derives from the Greek word "morph-," meaning shape or form, and *morphology* means the study of form(s). A well-known definition of morphology is the study of the internal structure of words. Researchers have been scientifically curious about understanding words since the first morphologist, Panini, who formulated the 3,959 rules of Sanskrit morphology in the 4th century BCE in the text "Astadhyayi" using a constituency grammar. The question of why morphology is so important could be answered by stating that if we need to understand the ultimate building blocks of the universe, we need to look at atoms, or in other words, its constituents. In the case of agglutinating language, these blocks are morphemes, the smallest meaning-bearing units of language. Morphological forms have a significant effect on phonology, syntax, and semantics in productive languages, as the operations in linguistic morphology have powers of deriving new word forms and inflecting words. To learn such languages, one needs to acquire a substantive set of rules for morphosyntax (Hankamer, 1989).

In linguistics, morphology refers to the mental system involved in word formation, the internal structure of words and how they are formed (Aronoff and Fudeman, 2011, p. 2). Words consist of stems and affixes; for example, the English word *opened* is formed by the concatenation of the stem *open* and the suffix *ed*. The phonological realization of individual morphemes is called as *morph*. Morphs in Turkish occur with alternations in vowels; for example, Turkish pluralization has two different morphs with the back vowel *a*, *çocuk-lar* "children" and the front vowel *e*, *ev-ler* "houses". Vowel alternations in Turkish are defined by a set of rules, which will be mentioned in section 2.2.4. We call morphemes with allomorphic forms *allomorphs*, these are morphemes carrying the same semantic information of their class with vowel alternations. In this study, we assume that the stems are free morphs that occur freely, while the suffixes must be bounded and called boundary morphemes.

Our focus on Turkish language arises from its productivity and morphologically rich nature. There are challenges regarding Turkish in terms of its morphological analysis. Controversially, morphologically simpler languages like English could be modeled in terms of word-based approaches due to their lack of productivity. Unlike agglutinating languages, in English, word forms could be stored in a word-based lexicon. Turkish has a large amount of word forms that cannot be stored in a word-based lexicon.

Furthermore, theoretically there could be infinite numbers of meaningful morpheme sequences in Turkish. The number of possible word forms that one can construct is infinite due to recursion. Recursion in Turkish is caused by morphemes that derive causative verbs and relative adjectives. One examples of the productivity of Turkish is described below:

Example 1.1:

OSMANLILAŞTIRAMAYABİLECEKLERİMİZDENMİŞSİNİZCESİNE

Where boundaries of morphemes are:

OSMAN-LI-LAŞ-TIR-AMA-YABİL-ECEK-LER-İMİZ-DEN-MİŞ-SİNİZ-CESİNE

where the -'s indicate the morpheme boundaries. The adverb in this example can be translated into English as "(behaving) as if you were of those whom we might consider not converting into an Ottoman." (Oflazer et al., 1994, p.2)

The diversity of morphological forms and syntactic rules in agglutinating languages causes a sparse distribution of forms. Turkish is a solid example of rich morphological diversity and productivity. In this study, the segmentation of Turkish morphology is motivated by a semi-supervised model with orthographic rules for allomorphs adopted as prior information. As a result, we aim to make use of Turkish allomorphy in clustering of phonological forms.

From a cognitive perspective, the importance of morphology arises in the acquisition of morphemes. When learning agglutinating languages, acquisition is a task of learning diverse morphological forms, classes, and their interactions. The learning of morphology entails segmenting words into morphemes. While there is evidence that word boundaries are learned during language acquisition (LA) of infants (Thiessen and Saffran, 2003), there is insufficient evidence about phonological and prosodic dimensions of the learning processes. In addition to the evidence about the significance of morphology in LA, the acquisition of morphemes includes a language-specific task unlike the universal grammar (UG) suggests. Several studies have provided evidence of the language-specific impact of nominal and verbal inflections on LA (Slobin, 1985; Bittner et al., 2003). These studies revealed that nominal inflections and verbal inflections differed in the developmental process of infants. This suggests that, LA is not dominated by innate structures; there is room for language-specific information and exposure more than UG suggests. If the distributional properties of different languages have an impact on linguistic levels, understanding their distributions may provide us with a basic understanding of how morphologically rich languages are acquired.

Statistical language modeling methods are based on machine learning methodologies categorized under three learning systems: First, in supervised learning, the system trains on a set of labelled corpus to identify the target function. Training data consist of the input and output values, whereby the system predicts unseen data with the function it inferred from the tagged data. It is difficult to tag all morphological phenomena of agglutinating languages like Turkish and overcome with computational expense. Furthermore, due to the high amount of possibility of a large amount of unseen data, training procedure of the model mostly underestimate possible word forms. Unlike supervised learning, the unsupervised and semi-supervised machine learning systems,

are more likely to be independent of extra information. However, in semi-supervised learning, training is motivated by extra information which is not found in the training set, while unsupervised models do not require any other information but untagged training data.

A computational model made of semantic information combined with the logical forms could explain a language beyond semi-supervised and unsupervised computational models for natural languages, the main concern about such models, arises from the computational expense. Çakıcı et al. (2016), reported results from the wide-coverage parser that consist of a semantically rich lexicon with lexicalized grammars involving. As a result of modeling lexicon paired with logical form or predicate-argument structure (PAS), training the parser with rich head informations improved parsing accuracy. Furthermore, the wide-coverage parsing with lexicalized grammars achieved to parse a wide range of constructions in Turkish, which no other parser able cover such wide-range of unique constructions. The wide-coverage parsing with such lexicon model proved itself to be a feasible model in contrary to computational concerns.

Natural language processing (NLP) applications are capable of processing language independently, but language-specific information needs to be involved within the process in order to obtain a better performing model. This study is to incorporate language-specific knowledge and the distributional properties of Turkish morphology from a form-driven perspective. Form-driven models may be deficient in covering the morpho-linguistic properties of language, but they give us clues about the distributional properties of morphology and boundary detection involvement in the acquisition of morphology. Additionally, as much as language learning explained unsupervised, the assumptions rely on innateness involve less. This study focuses on non-parametric Bayesian models for morphological segmentation and language learning. Our method differs from other non-parametric Bayesian models of Turkish by embedding orthographic rules into the clustering process where both bigram and unigram models involved. Therefore, our research questions are as follows:

1. How much of learning could be explained in terms of form-driven non-parametric Bayesian models, and is the word form enough to supervise the learning process?
2. Does supervising a non-parametric Bayesian model with orthographic rules as prior information result in better segmentations?

1.2 Role of Statistical Approaches in LA

The capability of LA is unique among human beings, as we have the ability to manipulate our linguistic knowledge and establish complex structures within the boundaries of our grammars, even in the absence of sufficient prior knowledge. Pinker (1995) demonstrated how the combinatorial rule system of human language is unique compared to other animals. Every human being is the master of her/his native language, regardless of his/her intelligence, DNA, race, etc. Humans are able to compose word forms by manipulating grammars of their languages unlike non-human animals. The acquisition of language, therefore, is the most mysterious topic in the cognitive sciences.

There are two mainstream approaches to LA. One is the nativist approach, in which LA is considered as cognitive resource that is an innate UG (Chomsky, 1965). UG suggests that all humans have a set of rules which are common to all natural languages. These rules are innate and can be updated (or reduced) in correspondence to the language children are exposed to. One supportive hypothesis is the Poverty of Stimulus (POS) argument (Chomsky, 1975). The POS argument suggests that it is impossible to acquire a language by exposure in the absence of negative evidence. The negative evidence here is correction of ungrammatical forms by adult speakers. The lack of negative evidence, expected to cause over-generalization in the language learning process. When an infant begins to learn a language, learning turns into the problem of narrowing down the set of UG into input language. Evidence shows that babies achieve a stable state even when there is a lack of corrections in primary linguistic data (PLD) (Gleitman and Newport, 1995). This suggests that humans have a system that is more sophisticated than what they are being exposed to.

Another argument supported by the nativist approach is the problem of ambiguity, which is related to the POS argument. For a baby, sentences (a) and (b) below are not problematic; they can acquire these syntactic constructs even there is lack of negative evidence in the environment (Crain and Pietroski, 2001).

- a) *John washed himself.*
- b) *John said that he thinks Bill should wash himself.*

Again Crain and Pietroski (2001, p.7) argued:

" So why do not children acquire a more permissive grammar, according to which 'himself' may depend on 'John' in (b), But if children allow multiple interpretations - e.g, the antecedent of 'himself' can be any prior term - no positive evidence would prove them wrong."

This evidence leads to the conclusion that humans have prior knowledge of the principle of the *binding theory*: a reflexive pronoun must be locally bound.

Regarding the learning of linguistic constraints, the nativist point of view suggests that constraints are also an innate capability of human beings. For example, the "wanna" and "want to" contractions (c) and (d) below are grammatical, but not (e). Children do not overgeneralize language due to their innate capacities.

- c) *I wanna go to school.*
- d) *I want you to go school.*
- e) **I wanna you to school.*

According to the continuity hypothesis (Pinker, 1991; Crain and Thornton, 1998), even when children make mistakes, they will never go beyond the boundaries of UG. The mistake of a child is a meaningful grammatical construction of another language because UG covers all possible human languages.

Pinker (1995, p.157) suggested, "That is, before children have learned syntax, they

know the meaning of many words, and they might be able to make good guesses as to what their parents are saying based on their knowledge of how the referents of these words typically act (for example, people tend to eat apples, but not vice versa)." If children can extract extralinguistic information before they start talking, negative evidence could still be out there, which could contradict the POS argument.

The computational approach to the concept of UG that argued by Cowie (1999) is in a more empiricist state, which presumes that exposure is more essential than innate knowledge in language acquisition. Cowie (1999) also suggested that there is an innate device in LA, but she also suggested that there is a computational process involved in it. Computational modeling of language is a useful approach to understand how much of LA can be explained in terms of exposure and innate knowledge.

1.2.1 Statistical Approaches to LA

Significant evidence of experience-dependent LA arises from Saffran et al. (1996), a research with eight month-old babies. The main aim of the research is to reveal how babies acquire language even in cases of a lack of exposure and to study the role of statistical cues on a child's learning capacity. To simulate exposure, a familiarization process applied that contains information about the target artificial language syntax without any other cues (pitch-accent, boundaries, prosodic components, phonetics, etc.). The experiment started with exposing babies to artificial language. In the second minute of exposure, babies were able to distinguish novel and familiar orderings of three-syllable strings. Furthermore, children can detect word and part-word boundaries by a longer period of exposure. Results suggest that, at least in early LA, experience plays an important role in acquiring transitional probabilities between parts of words.

Pelucchi et al. (2009) in their research, implemented the research method in Saffran et al. (1996) to natural languages. Two counterbalanced languages; Italian and Spanish are chosen as the experiment languages, instead of the artificial languages. Furthermore, eight-month-old native English monolingual infants were exposed to Italian and Spanish. Unlike Saffran et al. (1996), the eye gazing duration was used as the measurement method. Test items were distinguished by their backward transitional probabilities (BTP) and front transitional probabilities (FTP). The front and backward probabilities define the direction of adjacent syllables. Two identifiers, the low transitional probability (LTP) and high transitional probability (HTP), were used to measure child's sensitivity to their perception of LTPs and HTPs of words. The results (*ibid.*) revealed that children's sensitivity to BTP is significantly independent of the language group to which they belong. Additionally, children are capable of computing both FTP and BTP, but BTP has more coverage on data due to the structural properties of the babies' natural language.

Another approach by Wong et al. (2012) employed extra-linguistic information within perspective of grounded LA with respect to the evidential foundation of Carpenter et al. (1998) which, suggests that children who engage in joint attention with caregivers tend to have a faster learning process. The extra-linguistic input incorporated utterances, gaze, touch, etc. features, with the task of reducing the process to a proba-

bilistic context-free grammar (PCFG) learning, where syntax is sensitive to transitional probabilities. As result of this approach, the model allowed them to reveal the relationship between acquisition tasks in the study. Results revealed that it is important to use ideal learning models when investigating LA, and incorporating social cues with linguistic information could provide us important information about the significance of the extra-linguistic features in learning¹.

Lany et al. (2007) firstly, criticize the role of statistical cues in LA; their approach pointed to early language studies that were mainly nativist, due to a lack of knowledge about the distributional properties of languages. The study, focused on the artificial languages used in LA research and concluded that even though such models are arguable about their representational capacity of natural languages, but they provide a useful framework to understand LA. Artificial languages can be manipulated to observe and understand the effect of different transitional probabilities in learning without isolation from correlation with infants' prior knowledge. Lany et al. (2007) concluded that there is some computational processing in LA, but the features of the method and the method itself are still a mystery. The transitional probabilistic approach, chunking, and n-gram models do not fully explain or provide a comprehensive understanding of learning by themselves; therefore, further wide-coverage models should be developed to understand LA from a computational perspective.

1.3 Motivation of The Study

The aim of computational models of language is to model the language learning process based on certain assumptions. This study presumes that computational models may not correspond to the mind's internal structures, but they could represent and manipulate given data with respect to researcher's belief about the process to be modeled. Furthermore, computational modeling provides us knowledge to hypothesize how LA happens and a framework where empirical knowledge unifies with beliefs. Certain theories, hypotheses, and assumptions have been developed for to modeling of the data. In this section, firstly, internalist and frequentist reasoning methodologies of the modeling will be presented. Secondly, language of thought hypothesis (LOTH) (Fodor, 1975) presented as a foundational argument for cognitive models of mind. We neither oppose nor suggest an alternative hypothesis to LOTH. The only semantic dimension involved in this study is the semantic assumptions about Turkish phonology, such as allomorphy. We aim to discover how far morphology can be learned from the syntactic forms on the phonological dimension. With incorporating allomorphic information to our model, we aim to get a better clustering of phonological forms.

1.3.1 Frequentist vs. Bayesian Approach to Reasoning

There are two approaches to the statistical reasoning of data that influence modeling. The first approach is the frequentist analysis of data, which presumes that data are sufficient to understand themselves. The second approach is the internalist (Bayesian)

¹ child's eye (encoded as child.eye which represent gaze directions of child) is the most extra-linguistic information in learning.

view, suggesting that beliefs and prior knowledge should be involved in the analysis of data. The frequentist approach proposes that no subjective beliefs are involved in knowledge, but data are the knowledge itself, and observations could be measured from experimental results, with the perspective of "let data speak for themselves." However, in modeling we need to extract more knowledge than data and fixed parameters. The main difference between Bayesian and frequentist approaches is how probability is used to understand the data. Frequentists use probability with the purpose of data sampling. The Bayesian approach uses probability more widely to model both sampling and prior knowledge. The internalist (Bayesian) approach proposes that the probability is in a person's degree of belief about an event, not an objective measurement, as suggested by the frequentist approach. Lilford and Brauholtz (1996, p.604) argued that:

" when the situation is less clear cut (...) conventional statistics may drive decision makers into a corner and produce sudden, large changes in prescribing. The problem does not lie with any of the individual decision makers, but with the very philosophical basis of scientific inference."

This suggests that the classic statistical approaches may not necessarily be involved in the analysis of uncertain cases. Instead, Bayesian inference should be used for inferring knowledge due to its degrees of freedom for uncertainty. Geisler and Kersten (2002) suggested that the human visual capacity is best modeled in terms of Bayesian models in contrast to frequentist models. The computational studies of Marr (1982) and the evolutionary studies of Pinker (1997) are examples that are well explained and unified by the Bayesian framework. Bayesian inference is a fine graded reasoning framework for the philosophy of science with room for subjective information. Bayesian likelihood models can construct, eliminate, or hypothesize beliefs about data. Experiences, innate abilities, and beliefs are observable in human predictions, and the Bayesian reasoning has degrees of freedom to represent them within a likelihood model. Modeling the capability of the Bayesian approach also provides room for uncertainty. Humans' decision-making falls under uncertainty when trying to predict actions with insufficient data. Under uncertain conditions, human beings rely on their prior knowledge and try to decide which actions to perform based on experience. Learning a concept updates prior knowledge about certain conditions to reduce uncertainty. This probability is called subjective probability, which could successfully model uncertainty with Bayesian methods (Dagum and Horvitz, 1993).

1.3.2 LOTH

While form-driven approaches to language learning are limited by syntax, LOTH claims that the cognitive processes are combinatorial systems in which tokens are represented with both syntactic and semantic information as functions of syntactic tokens. Thus, any computational system aiming to model LA as a cognitive process needs to be governed by both syntax and semantic functions of syntactic tokens. LOTH (Fodor, 1975) assumes that thought and thinking occur in a mental language. If there was not a first language that enables language learning, the learning would fall into infinite regress. The LOTH is a system of representations in which representations are physically realized in the brains of the thinkers. The LOTH presumes that thought

is a token of a representation that has a syntactic (constituent) structure combined with its related semantics. Thus, thinking is a cognitive process in which combinatorial operations defined over representations are causally sensitive to the syntactic representations (tokens), in other words, thoughts have combinatory behaviour.

The LOTH is a hypothesis about the nature of thought and thinking that consist a family of ideas; causal-syntactic theory of mental processes (CSMP) and the representational theory of mind (RTM), about the way we represent our world. CSMP attempt to explain mental processes as causal processes defined over the syntax of mental representations and RTM claims, these mental representations have both syntactic structure and a compositional semantics. Therefore, thinking takes place in language of thought (LOT).

There are 3 main arguments for the LOTH: First, the LOT acquires the form of language, instead of imitating the grammar of a specific language. According to the hypothesis, the brain is capable of doing high-level abstractions so it can encode different formal communication methods and symbolic systems. Second, symbolic language is not equivalent to UG, but a common way of thinking and linguistic structure in all human thought. Fodor (1975) suggested that learning a language requires an internal mental language common to all human beings. Third, thinking is an abstract high-level process. While thinkers may have an idea about their thinking, there is no such access to the LOT. Only representations that are being tokened and the manipulation processes are visible to thinkers. The LOT is an innate device beneath manipulation and tokenizing that enables the manipulation of representations. Thus, the computational models of language learning are can not be one-to-one correspondent with mentalese but they try do deduce it from the logical form and the phonological form.

Unlike artificial languages, natural languages are accommodate uncertainty that, makes it harder to model with computational systems. But the LOTH provides degrees of freedom for computationalism, since both approaches are presume that, the concepts prevents learning from infinite regress are primitive. The point of computational models is to deduce the hidden layer between form with meaning, namely, grammar. Recent developments on artificial intelligence (AI) and formal logic, gives LOTH explanatory power within a naturalistic framework. Alan Turing's idea of a Turing Machine and Turing computability provides room for combination of computationalism with the LOTH. Turing's well-known experiment; the Turing test suggests that if a conversational agent (computational machine) is indistinguishable from a human being, then that machine would be an intelligent agent. According to LOTH, a combinatorial system with primitives would be a part of machinery of conversational agent.

1.4 Aim of The Study

The main aim of this study is to explore the cognitive plausibility of form-driven semi-supervised non-parametric Bayesian models with allomorphic priors in the morphological segmentation task. By adding orthographic rules as prior information, we aim to compare the results of the semi-supervised model with those of the unsupervised model to understand whether language-specific knowledge (allomorphic priors) has a significant effect on the segmentation task. Additionally, the affect of incorporating

morpheme co-occurrences into a form-driven computational model will be explored.

1.5 Scope

The scope of this study is Turkish words together with orthographic rules for morphological forms. Clustering morphemes as allomorphs may give us a better understanding of the learning process.

CHAPTER 2

BACKGROUND

2.1 Introduction

This chapter presents the linguistic and machine learning background used in this study to give a better understanding of methodologies to the reader. The chapter is organized into two sections: section 2.2 presents the linguistic background that involves the general concepts in morphology, syntax, and phonology with examples, and section 2.3 focuses on the machine learning background that our model is based on.

2.2 Linguistic Background

This section focuses on the linguistic knowledge essential to the segmentation task. The knowledge we will present is about morphology and its interaction with phonology and syntax.

2.2.1 Morphology

As stated in section 1.1, the term morphology is the study of the smallest meaning-bearing elements of a language, morphemes. Morphology is also an interface between phonology and syntax, where morphological forms as constituents carry both syntactic and phonetic information.

In productive languages like Finnish, Turkish, Tagalog, and Hungarian, morphemes can derive new word forms and modify the meaning of a word form. Thus, affixation in such languages causes words to have a complex internal structure. Productive languages contain a set of rules for morphological composition that are able to generate a considerable amount of word forms by the concatenation of morphemes (Hankamer, 1989).

Example 2.2.1 The word *certain* can have different word forms when combined with grammatical morphemes, as in the case of the words *uncertain*, *certainly*, *uncertainty*

Morphologically productive languages are called agglutinating languages. There are also languages without any morphology in which words consist of syllables, like Chi-

nese, Vietnamese, and Mandarin, which are called *isolating languages*.

2.2.2 Approaches to Morphology

This section presents some of the classical theories essential to morphology: the split morphology hypothesis, the amorphous morphology hypothesis, the item-and-arrangement and item-and-process morphology¹.

2.2.2.1 Split-Morphology Hypothesis

According to the split morphology hypothesis developed by Anderson (1982, 1992), Matthews (1972, 1991), and Perlmutter (1988), derivational morphology is too irregular to be combined with inflectional morphology; thus, they belong to separate components of grammar. Derivation is handled by lexical rules, while (regular) inflection is handled by syntactic rules. In this study, the segmentation task does not aim to distinguish between any inflectional and derivational morphemes, thus, they are treated as the same element.

2.2.2.2 Amorphous Morphology Hypothesis

In the amorphous morphology hypothesis, Anderson (1992) proposed that word structure is the output of an interaction between grammatical areas, and therefore it can not be localized to a single morphological component. According to this hypothesis, word structures cannot be explained merely by the concatenation of morphemes, but they can be explained by rule-governed relations among words with respect to the phonological internal structure assigned to words and eliminating morphologically motivated boundary elements. Amorphous morphology defines significant distinctions between inflection, derivation, and compounding, in terms of their place in a grammar.

Anderson exemplified his idea with the well-known Wakashan language K^wak^w'ala. every sentence is verb-initial, and some inflectional morphemes of noun phrases are not attached to constituents of the phrase, but instead to the verb, as shown in example 2.2.2 (from Anderson (1992)).

Example 2.2.2

<i>nanaq[ə]sil-ida</i>	<i>iʔg[ə]lâwat-i</i>	<i>[ə]liwinuxwa-s-is</i>	<i>mestwi</i>	<i>la-xa</i>
Guides-SBJ/ART	expert-DEM	hunter-INST-his	harpoon	PRE-OBJ/ART
<i>migwat-i</i>				
seal-DEM				

¹ For more recently presented two dimensional approach see Stump (2001).

" An expert hunter guides the seal with his harpoon."

Anderson (1992, p.19) further analysed the sentence as follows: "It is clear that if the morphology of $K^w ak^w ala$ is responsible for characterizing the internal form of phonological words, it will have to overlap heavily with the syntax in order to describe such facts. An alternative, however, is to suggest that the phonological word is not actually the domain of morphological principles of word structure." His theory of phonology and morphology naively involves into our work through analyzing surface forms according to the orthographic rules of Turkish, which we will describe in the upcoming sections.

2.2.2.3 Item-and-Arrangement and Item-and-Process Morphology

The morphological debate of mapping phonological forms to morphosyntactic forms was first identified by Hockett (1954). The item-and-arrangement hypothesis: both roots and affixes are treated as morphemes, item-and-process: roots are morphemes, but affixes are rules. These theories are the models for the mapping between phonological form and morphosyntactic information.

Item-and-process theories propose that a word is the result of an operation (morphosyntactic rules) applied to a root with some morphosyntactic features, which modifies the phonological form of syntactic unit. Example 2.2.3 shows a word formation rule for the application of the Turkish plural suffix *-lar* to a noun stem *kitap* 'book' results in a phonological sequence of the single word *kitaplar* instead of the composition *kitap-lar*.

Example 2.2.3 Word Formation Rule for Plural

$$\begin{aligned} & [+N] \\ & [+PLU] \\ & /X/ \rightarrow / X/ \\ & Kitap \rightarrow Kitaplar \end{aligned}$$

As presented in example 2.2.3, item-and-process morphology takes a morpheme as input and applies it to a stem, resulting in a new sequence of phonemes that cannot be broken into morphosyntactic parts.

In item-and-arrangement theories, words are considered as a set of morphemes consisting of a root affixed by a morpheme. In this model, sets are sequences made of phonological correspondences of roots and morphemes, as shown in example 2.2.4:

Example 2.2.4 $kitaplar \rightarrow kitap +lar$

root [+PLU]

Table 2.1: Partial paradigm of Finnish noun *talo* 'house'. From Roark and Sproat (2007, p.64).

category	Sing.	Plu
Nominative	talo	<u>talo-t</u>
Genitive	talo-n	<u>talo-j-en</u>
Partitive	talo-a	<u>talo-j-a</u>
Inessive	talo-ssa	talo-j-ssa
Elicative	talo-sta	talo-j-sta
Adessive	talo-lla	talo-j-lla
Ablative	talo-lta	talo-j-lta
Allative	talo-lle	talo-j-lte

Both theories are used frequently in morphology; the item-and-process approach was defended recently by Aronoff (1993), and item-and-arrangement theory accounted for the theory of distributed morphology (Halle and Marantz, 1993). Furthermore, Roark and Sproat (2007) also mentioned how both theories of morphology are suitable for different languages. For example, highly inflected languages, such as Classical Greek and Sanskrit, in which morphological rules are better explained in terms of word structure because of the rich information-carrying affixes. In this case, affixation is not simply a concatenation, but affixing a particular variant of the stem, this process also depends on the particular paradigm of a stem. Roark and Sproat (2007) also suggested that agglutinating languages, such as Finnish and Turkish, which have a systematical morphosyntax in a linear order, can be modeled in terms of morphemes rather than rules.

Finnish word *talo* reproduced at 2.1 exemplifies the regularities and irregularities (underlined forms) of Finnish nominal morphology. The irregular exceptions among plural affixes can be treated by encoding alternations as either conditional case selection in plural morphemes (-i/-j vs. -t) or defining two allomorphs, one with variant *-t* (in case of a NOMINATIVE affix) other with -i/-j variants.

Therefore, a systematic agglutinating language like Finnish can be explained in terms of item-and-arrangement. While Turkish is a morphologically complex language, morphotactics is clear enough to be explained in terms of finite state machines (Oflazer et al., 1994).

2.2.3 Morphemes as Syntactic Elements

As an example of multiple representations of allomorphs; the allomorph *-lar* in Turkish represents the forms *-lar* and *-ler* of plural suffixes. Unifying morphemes into allomorphs is a process of applying Turkish vowel alternation rules to the phonemes, with respect to the roundness and backness of the preceding vowel.

The high productivity of morphology presented in example 1.1, consists of free and bounded morphemes. **Free morphemes** most likely to occur freely, while **bounded morphemes** must be affixed to another morpheme. For instance, in the case of *disabling* formed by morphemes - *dis*, *-able* and *-ing*, *-able* is the **root** and free morpheme

of the word and other morphemes *-dis* is a **prefix** and *-ing* **suffix**. Roots are free morphemes that can not be further analyzed while a **stem** can not be broken into further parts. We can observe this difference clearly in compound words .

Example 2.2.5. The word form *skateboard* is a stem consists of two roots *skate* and *board*.

Furthermore, bound morphemes belong to different classes like **suffix**, **prefix**, **infix** and **circumfix** depending on their position of the concatenation to a stem.

Example 2.2.6. The word *decomposable* consists of *-de* as prefix *compose* as stem and *-able* as suffix.

Tuwali Ifugao, the language of the Philippines, uses circumfixes. For example, *ka-baddan-gan* 'helpfulness', formed by *ka-an* , a nominalizer circumfix and the verb *-baddang* 'help'.

Morphemes belong to small and closed classes, e.g., articles, locatives, and genitives, and occur more frequently than the words of open classes. Morphemes have a complex semantic relation with words from lexical categories, and are syntactically more predictable, by a deterministic finite state machine Turkish morphosyntax (Oflazer et al., 1994).

2.2.4 Turkish Morphology

Affixation process of Turkish, mostly occurs as the concatenation of suffixes to a stem, root, or another suffix, while prefixes are rarely seen. There is a range of suffixes in phonological terms, and allomorphs differ on the basis of their vowel harmony.

Surface forms of morphemes are often processed by morphophonemic operations for the grammatical construction of words. The grammatical composition of morphemes requires some morpho-phonological processes to ensure agreement between the affixed morpheme and the preceding vowel on the basis of **vowel harmony**. Under certain conditions, deletion, alternation, and drop rules on roots and morphemes are initiated; these rules are called morphophonemic operations that are part of morphophonemic processes.

2.2.4.1 Orthography of Turkish

The Turkish alphabet consists of 29 characters: 8 vowels: a, e, ı, i, o, ö, u and ü; and 21 consonants: b, c, ç, d, f, g, h, j, k, l, m, n, p, r, s, ş, t, v, y, and z. Vowels can be grouped to accumulate vowel harmony:

Table 2.2: Phoneme alternations of Turkish. (from Oflazer et al. (1994))

1. D : voiced (d) or voiceless (t)
2. A : back (a) or front (e)
3. H : high vowel (ı, i, u, ü)
4. R : vowel except o, ö
5. C : voiced (c) or voiceless (ç)
6. G : voiced (g) or voiceless (k)

1. Back vowels: {a, ı, o, u}
2. Front vowels: {e, i, ö, ü}
3. Front unrounded vowels: {e, i}
4. Front rounded vowels: {ö, ü}
5. Back unrounded vowels: {a, ı}
6. Back rounded vowels: {o, u}
7. High vowels: {ı, i, u, ü}
8. Low unrounded vowels: {a, e}

Oflazer et al. (1994) used meta-phonemes to describe the two-level morphology of Turkish, which we used in our allomorph filtering algorithm to map phonemes to allomorphs.

The phoneme alternations are shown in Table 2.2 are used for alternations in vowels, for example, *-lAr* is the allomorph for plural stands for both plural suffixes *-ler* and *-lar*. Meta-phonemes provides a useful notation for the two-level realization of allomorphs consisting of **surface form** and **lexical form**.

Example 2.2.7. Lexical form: bulut-lAr

N(cloud)-PLU

Surface form: bulut0lar bulutlar

Where *-lAr* represents the plural suffixes for two cases of metaphoneme A: the back vowel *a* or the front vowel *e*. One of them is chosen according to Turkish vowel harmony rules.

2.2.4.2 Morphophonemic Process

In Turkish, allomorphs are essential in the concatenation process, and variable vowels of an allomorph are called metaphonemes. Metaphonemes consist of six characters representing related vowels, as shown in Table 2.2. Rules of alternation depend on

vowels and their orthographic rules. Rules for vowel harmony are described as examples in which capital letters are metaphonemes of allomorphemes. '0' is the notation for deleted phonemes and morpheme boundaries.

In this study, rules are included in the segmentation model by a filtering algorithm for vowels. Processes on consonants aim to cluster Turkish morphological forms into allomorphic representations. The rules for vowel alternations are as follows:

Example 2.2.8. Low-unrounded vowels: If the last vowel of the preceding morpheme is a back vowel, metaphoneme A alternates to *a*.

Lexical form:	arkadaş-lAr	N(friend)-PLU
Surface form:	arkadaş0lar	arkadaşlar
Lexical form:	ayna-lAr	N(mirror)-PLU
Surface form:	ayna0lar	aynalar

Example 2.2.9 Low-unrounded vowels: If the last vowel of the preceding morpheme is a front vowel, metaphoneme A alternates to *e*.

Lexical form:	çiçek-lAr	N(flower)-PLU
Surface form:	çiçek0ler	çiçekler
Lexical form:	bebek-lAr	N(baby)-PLU
Surface form:	bebek0ler	bebekler

Example 2.2.10 High vowels: If the last vowel of the preceding morpheme is a back-rounded, metaphoneme H alternates to *u*².

Lexical form:	koşul-Hm	N(term)-1SG-POSS
Surface form:	koşul0um	koşulum
Lexical form:	macun-Hm	N(paste)- 1SG-POSS
Surface form:	macun0um	macunum
Lexical form:	koş-Hyor-yHm	N(run)-POSS
Surface form:	koş0uyor00um	koşuyorum

Example 2.2.11 High vowels: If the last vowel of the preceding morpheme is a front-rounded vowel, metaphoneme H alternates to *ü*

Lexical form:	üzüm-Hm	N(grape)-1SG-POSS
Surface form:	üzümm0üm	üzümüm
Lexical form:	göz-Hm	N(eye)-1SG-POSS

² cases ğ and ç excluded from our research due to our data does not contain any form with that characters.

Surface form: göz0üm gözüm

Example 2.2.12 High vowels: If the last vowel of the preceding morpheme is a back-unrounded vowel, metaphoneme H alternates to *ɨ*

Lexical form: gitar-Hm N(guitar)-1SG-POSS

Surface form: gitar0ım gitarım

Lexical form: zaman-Hm N(time)- 1SG-POSS

Surface form: zaman0ım zamanım

Example 2.2.13 High vowels: If the last vowel of the preceding morpheme is a front-unrounded vowel, metaphoneme A alternates to *i*

Lexical form: zafer-Hm N(victory)-1SG-POSS

Surface form: zafer0ım zaferim

Example 2.2.14 Consonant mutation: In Turkish, according to consonant mutation rule also known as *voicing*, if a morpheme ending with one of the voiceless consonants, *p, ç, t, k*, is concatenated with a suffix starting with a vowel consonants, voiceless consonant alternates to *b, c, d, g* respectively.

<i>biçak</i>	<i>biçag -im</i>	<i>kitap</i>	<i>kitab -i</i>
knife	knife -1.SG.POSS	book	book -ACC
'my knife'		'the book'	

Example 2.2.15 Consonant assimilation: If a morpheme starting with consonant D (see Table 2.2 for alternation rules) concatenates with a morpheme ending with one of the voiceless consonants *p, ç, t, k, g, h, s, ş, f* alternates to a *t* or *d*.

<i>yaprak</i>	<i>yaprak- ta</i>	<i>aç</i>	<i>aç -tı</i>
leaf	leaf -LOC	open	open -PAST
'at leaf'		'opened'	

2.3 Machine Learning Background

2.3.1 Bayesian Modeling

The Bayesian modeling³ expresses actual knowledge about the model parameters. A Bayesian probabilistic model⁴ is a parametrized joint distribution over variables. In

³ Bayesian modeling originates from Bayes theorem. Bayes theorem was proposed by Thomas Bayes (c. 1702 –17 April 1761), an English mathematician.

⁴ Typically interpreted as a generative model of the data.

Bayesian modeling, the actual model aims to infer posterior distribution $p(\theta|D)$, the probability of new parameters given data:

$$p(\theta | D) = \frac{p(D | \theta) p(\theta)}{p(D)} \quad (2.1)$$

where probability distribution $p(\theta)$ over the parameters is named *prior distribution*. For incoming data, the probability of information they contain is expressed with respect to model parameters named the *likelihood* of data $p(D | \theta)$ which is proportional to the distribution of the observed data given the model parameters and the $p(D)$ is *marginal probability*. The marginal probability of data is the probability calculated through all possible values of data used for normalization.

Bayes' theorem uses the likelihood and the prior to define the inverse probability distribution over parameters. The inverse probability distribution of parameters of the data called *posterior probability*. Posterior probability is the revised probability of parameter values occurring after taking into consideration the incoming data. To calculate the probability of new data, the theorem uses prior and likelihood. There are two cases according to the type of parameters: continuous or discrete:

$$p(D) = \sum_i p(D | \theta_i) p(\theta_i) \quad (2.2)$$

Continuous parameters:

$$p(D) = \int p(D | \theta) p(\theta) d\theta \quad (2.3)$$

Bayesian modeling defines the probability of an instance with respect to parameter values, latent variables⁵ or hypotheses. A Bayesian model is either parametric or non-parametric. The Bayesian parametric models are the Bayesian models with pre-defined parameters, we can call their parameters are constants defined by model designer. The Bayesian non-parametric models has countably infinite parameters that grows with the data.

2.3.2 Parameters and Conjugation

Integration over parameters bypasses the possibility of the biased estimation of parameters by integrating all possible values of the parameters. For example, if we have a set of segmentations S of a corpus C and latent variables are the segmentation points:

$$p(S | C) = \int p(S | C, \theta) p(\theta | C) d\theta \quad (2.4)$$

here θ is a set of parameters that are integrated out without being estimated. By integrating the parameters out, all possible values are carried out for the inference of latent variables without any estimation. The integration over parameters leads a more comprehensive inference of latent variables.

⁵ We integrate out the latent variables without estimating them.

When we adopt Bayesian modeling, the prior probability over parameters can be defined. A defined prior is also called a **conjugate prior** when the posterior distribution has the same form as the prior distribution.

For example, Gaussian distribution is self-conjugating by the Gaussian likelihood function, so if we choose Gaussian prior distribution, the posterior will be in Gaussian form. In the case of multinomial distribution, it has a conjugate prior in the form of Dirichlet distribution. The conjugation of a multinomial distribution with a Dirichlet prior results in a posterior distribution with a Dirichlet distribution form. Defining a multinomial distribution on $\{1, \dots, N\}$ possible outcomes and setting θ helps us to define **hyperparameters**. Here hyperparameters are parameters of prior distribution when we assume that θ is following some prior distribution. For the Dirichlet distribution prior, we can say that β is a hyperparameter for θ .

$$\begin{aligned} x_i &\sim \text{Multinomial}(\theta) \\ \theta &\sim \text{Dirichlet}(\beta) \end{aligned} \tag{2.5}$$

The first line of equation states that x_i is drawn from a multinomial distribution with parameters θ and in the second line states that, parameters θ are drawn from a Dirichlet distribution with hyperparameters β .

2.3.3 Dirichlet Distribution

Dirichlet distribution is the multivariate generalization of the beta distribution. We can conceptualize Dirichlet distribution with a probability mass function (PMF). The randomness of a bag of dice with different PMFs could be modeled with Dirichlet distribution. With respect to equation 2.5, Dirichlet distribution follows the form:

$$p(\theta | \beta) = \frac{1}{B(\beta)} \prod_{k=1}^K \theta_k^{\beta_k - 1} \tag{2.6}$$

where $B(\beta)$ is a normalising constant in a beta function form:

$$B(\beta) = \frac{\prod_{k=1}^K \Gamma(\beta_k)}{\Gamma(\sum_{k=1}^K \beta_k)} \tag{2.7}$$

where Γ is the gamma function defined as $\Gamma(t) = (t-1)!$ For positive integers.

2.3.4 Multinomial Distribution

If we suppose that each datum in one of k possible outcomes with a set of probabilities $\{x_1, \dots, x_k\}$, multinomial models the distribution of the histogram vector that indicates

how many times each outcome is observed over N total number of data points.

$$p(x | \theta) = \frac{N!}{\prod_{k=1}^K n_k!} \prod_{k=1}^K \theta_k^{x_k} \quad (2.8)$$

Where:

$$N = \sum_{k=1}^K n_k \quad (2.9)$$

Parameters θ_k are the probabilities of each data point k , and n_k is the number of occurrences of data point x_k .

2.3.5 Bayesian Posterior Distribution

In a conjugate Bayesian analysis, we have a multinomial likelihood with the Dirichlet prior. After observing n_k data, we have the posterior distribution for the parameters as Can (2011, p.53) derived:

$$\begin{aligned} p(\theta | x, \beta) &\propto p(x | \theta) p(\theta | \beta) \\ &= \frac{N!}{\prod_{k=1}^K n_k!} \prod_{k=1}^K \theta_k^{x_k} \frac{\prod_{k=1}^K \Gamma(\beta_k)}{\Gamma(\sum_{k=1}^K \beta_k)} \prod_{k=1}^K \theta_k^{\beta_k - 1} \\ &= \frac{N!}{\prod_{k=1}^K n_k!} \frac{\prod_{k=1}^K \Gamma(\beta_k)}{\Gamma(\sum_{k=1}^K \beta_k)} \prod_{k=1}^K \theta_k^{n_k + \beta_k - 1} \\ &= \frac{N!}{\prod_{k=1}^K n_k!} \frac{\prod_{k=1}^K \Gamma(\beta_k)}{\Gamma(\sum_{k=1}^K \beta_k)} \prod_{k=1}^K \theta_k^{n_k + \beta_k - 1} \\ &\propto \text{Dirichlet}(n_k + \beta_k - 1) \end{aligned} \quad (2.10)$$

Equation 2.10 yields a Bayesian posterior in Dirichlet distribution form when we conjugate β distribution, multinomial and Dirichlet distribution.

2.3.6 Inferring Multinomial Dirichlet

Can (2011, p.54) in her dissertation integrated out posterior mean using conjugacy as in equation Can 2.11:

$$\begin{aligned}
p(x_{N+1} = j \mid x, \beta) &= \int (x_{N+1} = j \mid x, \theta) (\theta \mid \beta) d\theta \\
&= \int \theta_j \frac{\Gamma(N + \sum_{k=1}^K \beta_k)}{\prod_{k=1}^K \Gamma(n_k + \beta_k)} \prod_{k=1}^K \theta_k^{n_k + \beta_k - 1} d\theta \\
&= \frac{\Gamma(N + \sum_{k=1}^K \beta_k)}{\prod_{k=1}^K \Gamma(n_k + \beta_k)} \int \theta_j \theta_j^{n_j + \beta_j - 1} \prod_{k \neq 1}^K \theta_k^{n_k + \beta_k - 1} d\theta \\
&= \frac{\Gamma(N + \sum_{k=1}^K \beta_k)}{\prod_{k=1}^K \Gamma(n_k + \beta_k)} \int \theta_j^{n_j + \beta_j - 1} \prod_{k \neq 1}^K \theta_k^{n_k + \beta_k - 1} d\theta \\
&= \frac{\Gamma(N + \sum_{k=1}^K \beta_k) \Gamma(n_j + \beta_j + 1) \prod_{k \neq 1}^K \Gamma(n_k + \beta_k)}{\prod_{k=1}^K \Gamma(n_k + \beta_k) \Gamma(N + \sum_{k=1}^K \beta_k + 1)} \\
&= \frac{n_j + \beta_j}{N + \sum_{k=1}^K \beta_k} \tag{2.11}
\end{aligned}$$

The posterior distribution of parameters in equation 2.11 are function as the prior distribution over the parameters. This yielded a rich-get-richer behaviour, where if previous observations of a given category are higher, then the next observation x_{N+1} has a higher probability of being in the same category.

If we consider both the probability of having a new category and of updating an existing category within an infinite number of elements:

$$p(x_{N+1} = j \mid x, \beta) = \begin{cases} \frac{n_j}{N + \sum_{k=1}^K \beta_k} j \in K \\ \frac{\beta_j}{N + \sum_{k=1}^K \beta_k} otherwise \end{cases} \tag{2.12}$$

There are two probabilities: for incoming data either there is a new data point or it will belong to an existing category. The probability for a data point that is assigned to an existing category is proportional to the number of data points in that category. Otherwise, the probability would be proportional to the hyperparameter defined for that category. This approach gives the advantage of natural smoothing for unseen data by leaving a probability space for them.

2.3.7 Bayesian Non-Parametric Modeling

Non-parametric models are models with an infinite number of parameters, contrary to what the name suggests. Dirichlet multinomial distribution consists of a fixed number of parameters and observations, and it is not always likely to have that kind of data in nature. For example, in language processing, there are infinite possibilities of morpheme segmentations in an agglutinating language like Turkish, as mentioned in Section 1.1. Therefore, a **Dirichlet process** (DP) is a natural consequence of modeling data with infinite parameters.

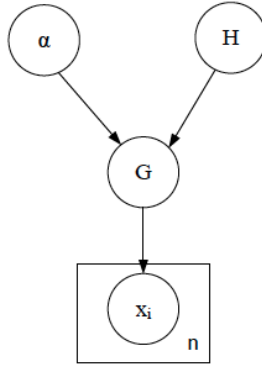


Figure 2.1: Plate Diagram of DP

A DP is a distribution over distributions. Unlike Gaussian distributions, a DP has non-finite, dimensional, discrete random distributions. Therefore, the process is classified as a non-parametric model. Dirichlet distribution allows flexibilities within data to be captured by its non-parametric stochastic structure.

Every distribution G should be distributed according to Dirichlet distribution with random sampling. Let H be a distribution over Φ and α be a positive real number. Then for any finite measurable partition A_1, \dots, A_n of Φ the vector $(G(A_1), \dots, G(A_n))$ is random since G is random (Teh, 2010). G is DP distributed with a base distribution H and concentration parameter α therefore, the formula could be written as follows:

$$G \sim DP(\alpha, H) \text{ if } (G(A_1), \dots, G(A_r)) \sim Dir(H(A_1), \dots, \alpha H(A_r)) \quad (2.13)$$

Each A is generated from a $DP(\alpha, H)$:

$$\begin{aligned} A_i &\sim G \\ G &\sim DP(\alpha, H) \end{aligned} \quad (2.14)$$

To obtain the probability distribution over G , which estimates future observations or latent variables we need to integrate out as discussed in the section above. Integration is applied for a future observation $x_{N+1} = j$ with Polya Urn Schemes (Blackwell and MacQueen, 1973)

$$\begin{aligned} p(x_{N+1} = j | x, \beta) &= \frac{1}{N + \alpha} \sum_{i=1}^N I(x_i = j) + \frac{\alpha}{N + \alpha} H(j) \\ &= \frac{n_j + \alpha H(j)}{N + \alpha} \end{aligned} \quad (2.15)$$

I is an identity function that returns 0 when $x_i \neq j$; otherwise it returns 1. This leads us to a well-known definition of a DP, known as Chinese restaurant process (CRP).

2.3.8 Chinese restaurant process (CRP)

The CRP is based on the definition of a restaurant with an infinite number of tables and an infinite number of seats, where each customer sits either at a new table or

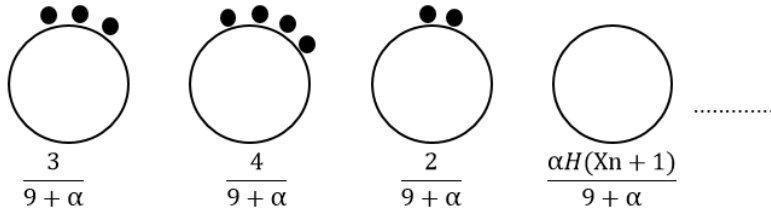


Figure 2.2: An illustration of CRP

an existing one. Each table has a unique menu to serve. The customer chooses an occupied table with a probability that is proportional to the number of customers who are already sitting at the table. If the chosen menu does not exist at any of the tables, the customer sits at a new table with a probability proportional to a defined constant α . While this process continues, tables with preferable menus will acquire a higher number of customers. Thus, the rich-get-richer principle shapes the structure of the tables.

As presented in Figure 2.2, if a customer x_{n+1} sits at an existing table, the probability will be defined by the number of customers already sitting at that table; otherwise, the probability will be calculated with respect to α and base distribution $H(x_{n+1})$. Other major definitions of DP are the stick-breaking process (Sethuraman, 1994; Ishwaran and James, 2001) and the Pitman-Yor process (Pitman, 1995; Pitman and Yor, 1997).

2.3.9 Hierarchical Dirichlet Process

The HDP consists of multiple DPs that are organized hierarchically with the DPs for all clusters sharing a base distribution, which itself is drawn from a DP. HDP is a dependency model for multiple DPs, which is more flexible than a single DP in uncovering group dependencies.

$$\begin{aligned}
 G_0 &\sim DP(\gamma, H) \\
 G_j &\sim DP(\alpha_0, G_0) \\
 \phi_{ji} &\sim G_j \\
 x_{ji} &\sim F(\phi_{ji})
 \end{aligned}
 \tag{2.16}$$

Equation 2.16 completes definition of HDP (illustrated in figure 2.3) where G_0 draws from a DP and $F(\phi_{ji})$ stands for factors of single representations of given categories (j). G draws from $DP(\alpha, G_0)$ this leads to a hierarchical structure where probability of a new customer depends both on G and G_0 .

The HDP treats each incoming datum as a restaurant instead of customers, and for each restaurant, there are seats for customers at its tables. The formula derived from Polya Urn Schemes, still valid in the HDP case, but by definition probability of unseen restaurants with unseen customers, is calculated according to G_0 , as shown in figure 2.3. In the case of incoming data, it does not exist as a DP but as the distribution of G_n , probability is proportional to concentration parameter α . If a restaurant or customer does not exist, probability is calculated according to G_0 .

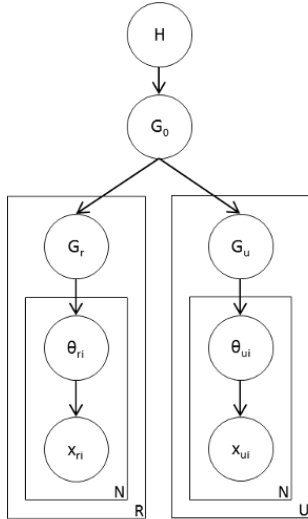


Figure 2.3: An illustration of HDP

2.4 Inference

In machine learning, the inference of parameters plays a significant role in estimation. While there are several approaches, like the maximum a posteriori (MAP) or maximum likelihood (ML), to perform the point estimation of parameters, we may need to estimate the posterior probabilities to understand the nature of parameters. Bayesian inference derives the posterior probability as a consequence of the prior probability and likelihood function. The true nature of Bayesian inference needs an estimation of the distributions over the possible values of the parameters. To estimate the parameters, we could use sampling by drawing random samples from their posterior distributions. Here we used the most common sampling method, Markov chain Monte Carlo (MCMC). The following section gives an intuition about this method.

2.4.1 Markov Chain Monte Carlo (MCMC)

A Markov chain is a mathematical model for stochastic systems whose states are governed by a transition probability where an actual state only depends on a previous state. MCMC is a simulation technique used to determine the probability distributions in a complex model. In MCMC, samples form a Markov chain where samples are drawn randomly. Let $S = \{S_1, S_2, \dots, S_1\}$ be a set of states with respect to their sequences:

$$p(P_{n+1} = x \mid X_1 = x_1, \dots, X_n = x_n) = p(P_{n+1} = x \mid X_n = x_n) \tag{2.17}$$

2.4.1.1 Metropolis-Hastings Algorithm

The Metropolis-Hastings algorithm was developed by- Metropolis et al. (1953) and generalized by Hastings (1970). The Metropolis-Hastings algorithm, after drawing random samples, determines whether to retain the sample according to an acceptance rule.

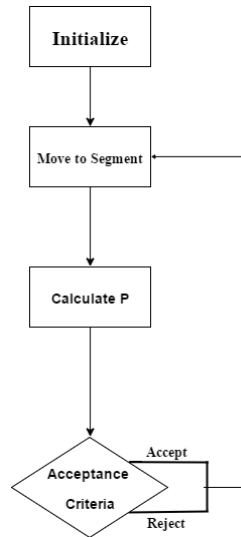


Figure 2.4: Diagram of Metropolis-Hastings Algorithm

The algorithm works on random draws from a distribution. With each iteration, the algorithm determines an accept/reject state with respect to the probability of parameters. With each iteration, the algorithm gets closer to inducing the target distribution from random samples.

CHAPTER 3

LITERATURE REVIEW ON UNSUPERVISED LEARNING OF MORPHOLOGY

3.1 Introduction

This section presents computational approaches to morphology and previous studies on non-parametric learning models. The present study covers morphological segmentation models based on the minimum description length (MDL), maximum likelihood estimation (MLE), maximum a posteriori (MAP), and parametric and non-parametric Bayesian approaches with a computational frame.

3.2 Statistical Models of Learning of Morphology

Statistical models are mathematical models consisting of equations that are actual beliefs about data. In the morphological segmentation task, the model learns morphology by mathematical equations and outputs the morphological analysis of a word.

There are different approaches to the segmentation task; in this section, some of the mainstream approaches are covered.

3.2.1 Letter Successor Variety (LSV) Models

Successor variety (SV) was first proposed by Harris Harris (1955) as a segmenting method that transcribes spoken language utterances into morphemes. SV here is the number of letters that can follow each letter in a word. The main idea is counting letter successors for each letter to detect morpheme boundaries. If a letter has a significantly high count of letter successors within an utterance, a new morpheme boundary is suggested.

Example 3.2.1 LSV would process an utterance *modeling* letter by letter, until the model is unable to identify any boundaries due to the low letter successor count. Then, the actual count rises because of the number of possible morphemes (ie. *-ing*, *-ed*) already incremented letter successor points for letter *I*.

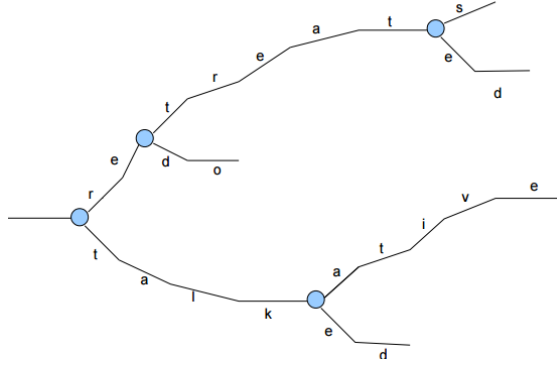


Figure 3.1: Word split points in a LSV model
(taken from Can and Manandhar (2014))

Figure 3.1 visualizes splitting points as a tree structure where nodes are splitting points and branches address the letter sequences of splits. Harris manually defined *cutoff* values, which affect the segmentation points (bigger values cause the under segmentation of morphemes while lower values cause over segmentation). Following Harris (1955), LSV is used as a measure for the segmentation of words into morphemes (Hafer and Weiss, 1974; Déjean, 1998; Bordag, 2005; Goldsmith, 2006; Bordag, 2008; Demberg, 2007).

Hafer and Weiss (1974) extended LSV by using predecessor and letter successor varieties to find segments and choosing the stem. Their approach suggests an improvement on LSV by replacing counts with entropies. Their study proposed four improvements on *cutoff*, *peak* and *plateau*, complete word and entropy. The entropy could be calculated as follows:

$$E(k_i) = \sum_{j \in \Sigma} \frac{C_{k_i}}{C_{k_{ij}}} \log_2 \frac{C_{k_i}}{C_{k_{ij}}} \quad (3.1)$$

Where i is the letter prefix of the word k and $E()$ is a function that returns letter successor entropy (LSE) of an affix. k_i . C_{k_i} is the total number of words in the corpus matching with the letter i of the word k and $C_{k_{ij}}$ is the number of words in the corpus matching with the letter i with successor j . This approach has an advantage over earlier version because the LSE improves the morpheme boundary detection of morphemes with LSV counts.

Déjean (1998) suggested another improvement on LSV method, such as three phases with a most frequent morpheme dictionary. The first step is to create a most frequent morpheme dictionary in which frequencies are obtained by LSV. The second phase involves using a morpheme dictionary to generate additional morphemes for words in the corpus, and the third phase is the final analysis on the corpus with a new morpheme dictionary.

Bordag (2005) combined context information and LSV to reduce the noise and irregularities of LSV outputs. The context information he used includes syntactic similarity with respect to syntactic classes of words. The first step is computing the

co-occurrences of adjacent words of a given word W by its log-likelihood. The obtained set of significant adjacent words is called "neighborhood vectors." In his second step, he calculated the similarity of the vectors by common words within different vectors and clustering.

Example. 3.2.2 Considering a corpus of words in which the, word *painting* co-occurs with a vector of words (*paint, coloring, walking, playing*), the highest number of adjacent different word forms for the words *painting* and *playing* is 70.

In his further research, Bordag (2006) used an algorithm consisting of two steps. The first step entails using the LSV; the second step is to insert analyzed words into a *trie*¹ classifier by morphemes and their frequencies. To analyze a word, *trie* is searched until the correct branches providing the right segmentations are revealed..

3.2.2 MDL Based Models

MDL is an information theoretic model for the learning of morphology. The MDL principle was first introduced by Rissanen (1978), as in Occam's razor the best description of data or the best hypothesis is the one that leads to the best compression of the data. Grünwald (2005) made a clear statement:

"[The MDL Principle] is based on the following insight: any regularity in a given set of data can be used to compress the data, i.e. to describe it using fewer symbols than needed to describe the data literally."

The MDL theory is grounded on one-to-one correspondence between length functions and probability distributions. For a probability distribution p , the length of probability measure $p(x)$ is equal to $-\log_2 p(x)$ where it minimizes the expected description length. From a Bayesian perspective, MDL can be used as the prior for model M :

$$\begin{aligned} \operatorname{argmin}_M [-\log_2 p(M | C)] &= \frac{-\log_2 [p(C | M) p(M)]}{-\log_2 [p(x)]} \\ &\propto \log_2 [p(C | M) p(M)] \end{aligned} \quad (3.2)$$

Table 3.1: Input Words

walk	referral
walks	refer
walked	refers
walking	dump
referred	dumps
referring	preferential

Table 3.2: Stem Table

stem	code
walk	1
referr	2
refer	3
dump	4
preferenti	5

Table 3.3: Suffix Table

suffix	code
NULL	1
s	2
ed	3
ing	4
al	5

Brent et al. (1995) defined two models to solve the morpheme discovery problem: the first model is called simple recombination; it encodes a list of words with binary sequences of stems and suffixes in which the stems are kept in tables, as illustrated in

¹ Look for Fredkin (1960) and Morrison (1968) for *trie*.

stems	suffixes
guitar	null
table	ed
car	ing
book	e
bottle	s
curse	es
the	
glass	

Table 3.4: Encoded words

Stem	Suffix	Stem	Suffix
00	00	01	110
00	01	100	00
00	100	100	01
00	101	101	00
01	100	101	01
01	101	1100	110

Tables 3.1, 3.2, 3.3, and 3.4. The most frequent stems and suffixes are encoded with shorter encodings. The optimal length of each code word is achieved by Shannon-Fano (SF) coding (Brent et al., 1995). Final segmentation is chosen when the morphological analysis results in a minimum code.

Goldsmith (2001, 2006) proposed Linguistica, a state-of-the-art system for unsupervised morphology learning. Linguistica uses signatures to encode the data, where signature is a representation of the inner structure of a list of words that containing affixes. Figure 3.2 presents the structure of a signature, where signatures are pointers for stems and suffixes. In addition, there are two more lists for stems and suffixes that contain letters.

Here M is the morphology minimizing the objective function for the best morphology in the corpus. The length of M gives information about the shortness of the morpheme where this information is simplifying the decision of possible morpheme and the second term calculates how well the model fits the corpus.

$$DescriptionLength(Corpus = C, Model = M) = length(M) + \log_2 \frac{1}{p(C|M)} \quad (3.3)$$

The log probability of a given word w , is analysed as belonging to given signature σ with stem t and suffix f , is as follows:

$$p(w = t + f) = p(\sigma)p(t|\sigma)p(f|\sigma) \quad (3.4)$$

Another state-of-the-art system within the MDL principle is Morfessor, proposed

$$\begin{array}{l}
\left\{ \begin{array}{l} \textit{SimpleStem} : \textit{car} \\ \textit{SimpleStem} : \textit{table} \\ \textit{SimpleStem} : \textit{guitar} \end{array} \right\} \left\{ \begin{array}{l} \textit{NULL} \\ s \end{array} \right. \\
\\
\left\{ \begin{array}{l} \textit{SimpleStem} : \textit{book} \\ \textit{SimpleStem} : \textit{bottle} \\ \textit{SimpleStem} : \textit{curse} \end{array} \right\} \left\{ \begin{array}{l} \textit{NULL} \\ ed \\ s \\ ing \end{array} \right. \\
\\
\left\{ \textit{SimpleStem} : \textit{glass} \right\} \left\{ \begin{array}{l} \textit{NULL} \\ es \end{array} \right. \\
\\
\left\{ \textit{SimpleStem} : \textit{the} \right\} \left\{ \textit{Null} \right.
\end{array}$$

Figure 3.2: A sample morphology with signature pointers and tables, taken from Goldsmith (2006)

tables are covering words: *car, cars, table, tables, guitar, guitars, book, books, booking, booked, curse, cursed, cursing, curses, glass, glasses, the.*

by Creutz and Lagus (2002). Morfessor² aims to construct a model consisting of a morpheme vocabulary named *codebook* and a sequence of text as the input. The MDL cost function is employed to identify the succinct representation of words and data:

$$\begin{aligned}
C &= \textit{Cost}(\textit{Data}) + \textit{Cost}(\textit{Codebook}) \\
&= \sum_{k \in D} -\log p(m_k) + \sum_{j \in M} i \times l(m_j)
\end{aligned} \tag{3.5}$$

where D is a set of morpheme sequences that constructs words, and M is the morpheme codebook which consists of morpheme types. First term of the equation, the length of data is calculated by ML estimate³ of morphemes denoted by $P(m_k)$ negative log-likelihood of ML to calculate the cost of the source text. The second term is the cost of the codebook, calculated by the summation of all morpheme lengths $l(m_j)$ where i is the number of characters that encode a character.

The search algorithm employed here proceeds recursively; a word assumed to be a morph at the beginning of the process and appended to the codebook. Every possible split of the word is evaluated into two parts, and the codebook is used to generate an updated corpus.

3.2.3 Maximum Likelihood Based Models

The MLE method aims to determine the most likely function explaining the observed data. In morphological segmentation, ML assigns probabilities to morphemes with

² Morfessor is a family of models for morphological segmentation and algorithms; here we present the first published member of the family.

³ the token count of morphs divided by the total count of morph tokens

respect to the cost function. MLE uses no prior information; therefore, no bias is involved in the model, and the model maximizes the likelihood function:

$$M_{MLE} = \underset{i}{\operatorname{argmax}} p(D | M_i) \quad (3.6)$$

Creutz and Lagus (2002) proposed a second method within their Morfessor baseline family that employs MLE instead of the MDL principle. The model employs the expectation maximization (EM) algorithm to calculate the optimal cost. The cost function is the likelihood of the data:

$$\operatorname{Cost}(C) = \sum_i -\log p(m_i) \quad (3.7)$$

where the summation is over all morph tokens in the corpus C . As MDL version mentioned in section 3.2.2, $p(m_i)$ used to calculate probability of morpheme.

Creutz and Lagus (2004) developed another ML-based version of Morfessor, Categories ML. The difference between the baseline ML and Categories ML is the first-order Markov chain. In Categories ML, the Markov chain assigns probabilities to each possible split of word form unlike the baseline ML. Furthermore, morphemes as categorized as suffixes, prefixes, or stems. The model consists of the bigrams of morphemes constructing a word $w = m_1, m_2, \dots, m_n$ and the Markov chain follows as:

$$p(m_1, m_2, \dots, m_n | w) = \left[\prod_{i=1}^n p(C_i | C_{i-1}) p(m_i | C_i) \right] p(C_{k+1} | C_k) \quad (3.8)$$

Where $p(C_i | C_{i-1})$ is the bigram probability of a transition between morph categories. The probability of observing the morph m_i with the selected category is $p(m_i | C_i)$. The categories $p(C_{k+1} | C_k)$ represent word boundaries. Category membership probabilities $p(C_i | m_i)$ are estimated by a perplexity measure. Perplexity measures the predictability of the preceding or following morph with relation to a specific target morph. EM is employed to estimate the probabilities in each iteration after re-tagging the words using the Viterbi algorithm. The bigram model has an advantage over unigram models with its sensitivity to dependencies of co-occurring morphs.

ParaMor (Monson et al., 2008) extended their work by assigning the likelihood for each morpheme before applying segmentation (Monson et al., 2009). The system works by counting the frequencies of word-final strings on shared word-initial strings in a list of annotated words. Probabilistic ParaMor processes on outputs of ParaMor with a tagger trained on results in order to assign the likelihood for each morpheme boundary. Their finite-state tagger (Hollingshead et al., 2005) determines the tagging of an input, such as a morpheme for each character of given word.

3.2.4 Maximum A Posteriori Based Models

MAP has a prior containing a bias about the data $p(M_i)$ unlike ML estimation. Creutz and Lagus (2005) proposed a new member of the Morfessor family, which aims to cover

compositionality. The system uses a hierarchical lexicon in which a morph can consist of either a string of letters or two submorphs, which recursively consists of submorphs. As in Creutz and Lagus (2004), words are represented by Hidden Markov Models (HMMs), by categories (prefix, suffix, stem, and non-morpheme). The prior in this model has two parameters. One of them is meaning and the other one is form. The form is how a morpheme occurs in the corpus with respect to its substructure, and the meaning consists of features such as length, frequency, and right/left perplexity of the morpheme. Therefore, a lexicon M is made of two parts of morpheme m_i :

$$P(\text{lexicon}) = M! \cdot \prod_{i=1}^M P(\text{meaning}(m_i)) \cdot P(\text{form}(m_i)) \quad (3.9)$$

$$M_{MAP} = \underset{i}{\operatorname{argmax}} p(D | M_i) p(M_i)$$

where $M!$ represents the possible orderings of the morphs in the lexicon.

3.2.5 Bayesian Parametric Models

The Bayesian models discussed in Section 2.2 play a significant role in morphological segmentation. Creutz (2003) proposed a generative probabilistic model based on Brent (1999) with a more precise probability distribution of morpheme lengths. The generation process starts with determining the number of morphs n_m in the morph lexicon, where probabilities $p(n_m)$ has a uniform distribution. The gamma distribution is used to choose the length in characters:

$$p(l_{m_i}) = \frac{1}{\Gamma(\alpha)\beta^\alpha} l_{m_i}^{\alpha-1} e^{-l_{m_i}/\beta} \quad (3.10)$$

Where l_{m_i} is the length of morph i in characters, α and β are the constants, and $\Gamma(\alpha)$ is the gamma distribution. After morphs are drawn from the distribution, the decision of the target morpheme sequence is made with the total probabilities of morphemes calculated by the ML of each character c_j :

$$p(c_j) = \frac{n_{c_j}}{\sum_k n_{c_k}} \quad (3.11)$$

Where n_{c_j} is the frequency of character c_j in the corpus and $\sum_k n_{c_k}$ is the total number of characters in corpus. Then the lexicon is created without considering ordering of morphemes:

$$p(\text{lexicon}) = p(n_m) \prod_{i=1}^{n_m} \left[p(l_{m_i}) \prod_{j=1}^{l_{m_i}} p(c_j) \right] \cdot n_m! \quad (3.12)$$

Where $n_m!$ states all possible orderings of n_m elements. After lexicon created, next step is to generate a corpus by morph lexicon obtained. Morpheme frequencies obtained by Mandelbrot's Zipfian formula definition⁴. The probability of a particular order is the inverse of the multinomial; therefore, the probability of the corpus is:

⁴ See Baayen (2001) for detailed information about zipfian law and word frequency distributions

$$p(\text{corpus}) = \left(\frac{N!}{\prod_{i=1}^{n_m} f_{m_i}!} \right)^{-1} \quad (3.13)$$

where the numerator N is a result of the summation of the morpheme frequencies in the model, and the denominator is the product of the factorial of the frequency of each morpheme in the model. The search for the optimal model is handled with the same recursive algorithm in the Morfessor baseline (Creutz and Lagus, 2002). The results indicate that the usage of prior information has a significant effect on the accuracy of the algorithm.

3.2.6 Bayesian Non-parametric Models

A Bayesian non-parametric model is a Bayesian model, defined on an infinite-dimensional parameter space. The parameter space is typically chosen as the set of all possible solutions for a given learning problem (Teh, 2010).

Goldwater et al. (2005) developed a two-stage model by extending the CRP. The system generates these cluster labels first by drawing a class, then drawing a stem and a suffix conditioned on the class where draws are from a multinomial distribution:

$$p(l_k = w) = \sum_{c, t, f} I(w = t + f) p(c_k = c) p(t_k = t | c_k = c) p(f_k = f | c_k = c) \quad (3.14)$$

Where c_k denotes the class label, t_k denotes the stem, and f_k denotes the suffix associated with a word constructed by the concatenation of t and f .

Can and Manandhar (2012) proposed a model to capture the morphological paradigms that are structured within a hierarchy. Their likelihood function is defined to process recursively under subtrees of words:

$$p(D_k | T_k) = (D_k) (D_l | T_l) (D_r | T_r) \quad (3.15)$$

where T_l and T_r are left and right subtrees, and the likelihood is decomposed recursively until the leaf nodes are reached. Two DPs defined to generate stems and suffixes. Each node generated from a DP is independent from other nodes.

CHAPTER 4

METHODOLOGY AND RESULTS

4.1 Introduction

The model we are using consists of two versions, unigram and bigram HDP models. The Metropolis Hastings algorithm is employed for inference. Probabilities drawn from Dirichlet distributions are calculated with Markov chains. Segmentations are generated randomly, and for each segmentation in which a new segment is generated, the algorithm determines whether a new segmentation is accepted or rejected.

Our corpus C is a set of words as $C = \{w_1, w_2, w_3, \dots, w_n\}$, where each word consists of random split segmentations $w_n = \{s_1 + m_1, \dots, +m_n\}$. Here s_1 is the first segment of w_n assumed to be a stem and m_n as suffix. As a result, we have a set of data points D with $w_n = s_n + m_n$ for each word.

$$D = \{w_1 = s_1 + m_1, \dots, w_n = s_n + m_n\}$$

We have defined two different models as unigram and hierarchical bigram to observe how our approach performs with different parameters and perspectives on the data. Figure 4.1 presents an intuitive general overview of the model which, this chapter aims to explain the process in detail.

4.2 Allomorph Filtering

Our filtering algorithm applies the rules given in Table 2.2 in which different forms of the same morphemes are clustered into allomorphs with respect to vowel alternations. Morphophonemic rules are applied to each generated segmentation by filtering the algorithm. The filtering in the unigram model given as follows:

$$w_i = s + m_{1f} + \dots + m_{nf} \tag{4.1}$$

Where s is the first generated segment i.e. stem of w_i and m_i refers to a suffix in w_i . We assume that each generated segment for a word is independent from the others and segments have a stem succeeded by a suffix; thus, filtering is only applied to segments assumed as suffix, if there is more than one segment. The f indicates that

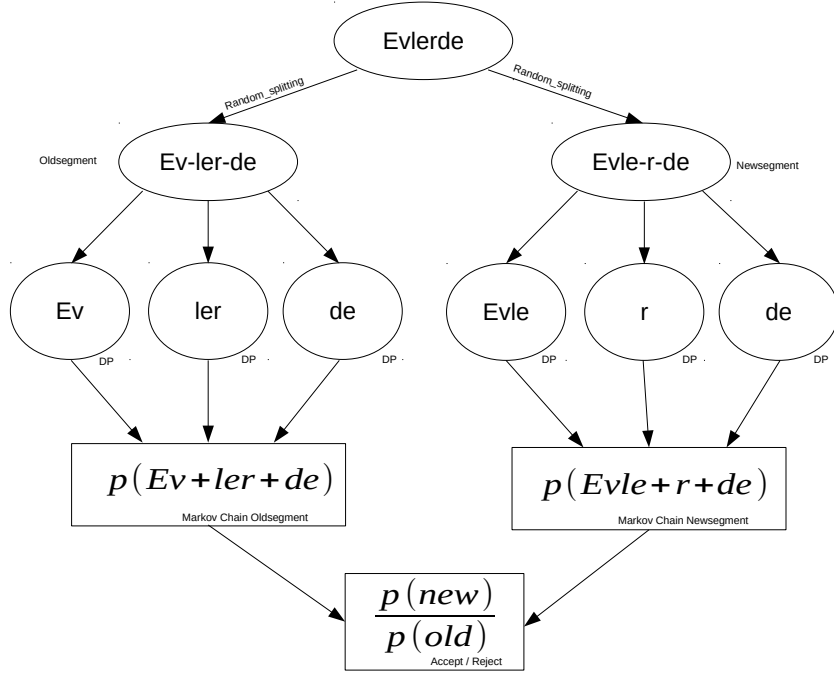


Figure 4.1: An overview of the model

The initial word *Evlerde* randomly splits into the segment sequence *Ev-ler-de* then probability of each segment drawn from a DP which forms a Markov Chain. The same procedure applies to initial word respectively to generate newsegment. The newsegment of the word accepted or rejected according to acceptance criteria.

the morpheme is filtered by algorithm 1. The algorithm takes a string as input and replaces defined characters with their allomorph correspondents with the exception of suffix '*ken*' which does not show any allomorphy.

4.3 Unigram Model

We have defined a DP to generate segments with the assumption that morphemes are independent from each other, and the first segmentation of a word is recognized as a stem based on the assumption that stems are always concatenated with suffixes, but not prefixes. The probability of a morphological segmentation of a word is defined as follows:

$$p(w = s + m) = p(s) p(m) \quad (4.2)$$

In the unigram model, we assume that stems are also independent from suffixes; therefore, probability of a word is independent of co-occurrences of stems and suffixes. The probabilities of each segment drawn from a DP are determined as follows:

$$\begin{aligned} G_s &\sim DP(\alpha_s, H_s) \\ s &\sim G_s \end{aligned} \quad (4.3)$$

Algorithm 1 Filtering Algorithm

```
1: input:  $D = \{w_1 = s_1 + m_1, \dots, w_n = s_n + m_n\}$ 
2: procedure FILTER
3:    $chars \leftarrow \{ 'd' : 'D', 't' : 'D', 'a' : 'A', 'e' : 'A', 'B' : 'H', 'i' : 'H', 'u' : 'H', 'C' : 'C', 'g' : 'G', 'k' : 'G' \}$ 
4:    $segment \leftarrow string$ 
5: top:
6:   if 'ken' in segment then
7:      $exchar \leftarrow getindex(string)$ 
8: loop:
9:   if chars in segment[i] then
10:     $replace(segment[i], chars[i])$ 
11:
12:   if exchar True then
13:     $replace(segment[exchar], 'ken')$ 
14: return segment
15: for all m in w do :
16:   return: Filter(m)
```

Where $DP(\alpha_s, H_s)$ denotes a DP, distribution over segments, and G_s is the random probability distribution that is distributed according to DP. Here α_s is a concentration parameter that adjusts sparsity of distribution. Large values of α_s leads a higher number of segments, while low values reduce number of segments generated per word. $\alpha_s < 1$ results in sparse segments and a skewed distribution; on the other hand $\alpha_s > 1$ leads to a uniform distribution that assigns closer probabilities to segments. If $\alpha_s = 1$ all segments are equally probable and uniform among all data points provided. Therefore, the concentration parameter is a constant defining the uniformity of a distribution. Teh (2010) referred to a concentration parameter as a strength parameter when a DP is used as a prior of the Bayesian non-parametric model. We use $\alpha_s < 1$ with respect to sparse distribution of Turkish morphology to prevent bias over morphemes.

H_s is the base distribution that determines mean of the DP (Teh, 2010). The base distribution can be continuous or discrete. We use geometric distribution of the morpheme lengths for the base distribution:

$$H_s = \gamma^{|s|} \quad (4.4)$$

where exponent $|s|$ indicates the length of a morph and γ is a gamma parameter ($\Gamma < 1$).

After probability distribution G_s is drawn from DP, words can be generated by drawing segments from G_s . As mentioned in Section 2.2 we integrate out probability distribution G , instead estimating them. After integration, the joint probability distribution becomes:

$$p(s_1, s_1, \dots, s_N) = \int p(G_s) \prod_{i=1}^N p(s_i | G_s) dG_s \quad (4.5)$$

where K denotes the total number of segment tokens. The joint distribution of seg-

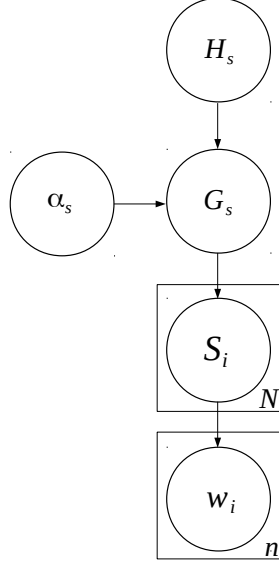


Figure 4.2: The plate diagram of the unigram model
 w_i is the word generated from a DP. s_i represents segments that form the word and the rectangular boxes show how many times the process is repeated.

ments leads to the CRP. The CRP provides the probability of each segment. Therefore, the joint probability distribution of segments $S = \{s_1, s_2, \dots, s_N\}$ becomes:

$$\begin{aligned}
 p(s_1, s_2, \dots, s_N) &= p(s_1)p(s_2) \dots p(s_N) \\
 &= \frac{\Gamma(\alpha_s)}{\Gamma(N + \alpha_s)} \alpha_s^K \prod_{i=1}^K H_s(s_i) \prod_{i=1}^K (n_{s_i} - 1)! \quad (4.6)
 \end{aligned}$$

where K denotes the number of unique segments. The second and third factors of the equation correspond to the case in which new segments are generated for the first time; the last factor corresponds to the case segments generated n_{s_i} times. The first factor consists of all denominators from both cases. The conditional probability of a segment, calculated according to the CRP described previously, generated segments:

$$p(s_i | S^{-s_i}, \alpha_s, H_s) = \begin{cases} \frac{n_{s_i}^{S^{-s_i}}}{N^{S^{-s_i}} + \alpha_s} & \text{if } s_i \in S^{-s_i} \\ \frac{\alpha_s * H_s(s_i)}{N^{S^{-s_i}} + \alpha_s} & \text{else} \end{cases} \quad (4.7)$$

where $n_{s_i}^{S^{-s_i}}$ denotes total number of the same type segments with s_i , but the new instance of the segment excluded where S^{-s_i} is the segments that segment token s_i excluded. $N_{s_i}^{S^{-s_i}}$ is the total number of segments in S where segment s_i excluded.

4.4 HDP Bigram Model

The bigram model is identical to the unigram model; unlike the independence assumption in the unigram model, bigram model consider co-occurrences of adjacent morphemes. Furthermore, stems are distinguished from suffixes to provide a better segmentation of stems. Within this approach, equation 4.3 turns into:

$$p(w = s + m) = p(s) p(m|s) \quad (4.8)$$

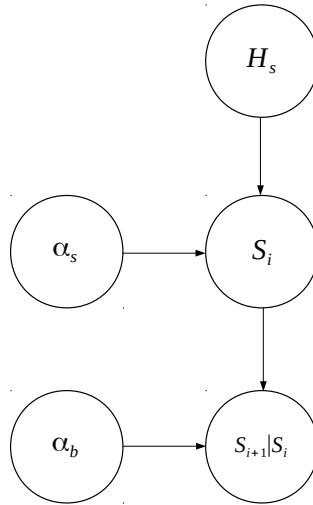


Figure 4.3: The plate diagram of the bigram HDP model
 w_i is the word generated from a DP. s_i represents segments that form the word and the rectangular boxes show how many times the process is repeated.

which assumes a stem generated could occur freely, but concatenated suffixes occur according to adjacent suffixes. Word with multiple segments calculated with respect to dependencies:

$$p(w = s_1 + s_2 + \dots + s_n) = p(s_1) \prod_i p(s_{i+1}|s_i) \quad (4.9)$$

Here, the first segment of the word is generated from a Dirichlet process and bigrams are generated from another Dirichlet process. We use a hierarchical Dirichlet process with two levels, where first we generate the first segment through a Dirichlet process and in the second level we generate the following segment depending on the previous segment through another Dirichlet process. HDP consists of multiple DPs within a hierarchy and is able to model between-group dependencies (see Figure 4.3). The bigram hierarchical Dirichlet process model is defined as follows:

$$\begin{aligned}
s_{i+1} | s_i &\sim DP(\alpha_b, H_b) \\
H_b &\sim DP(\alpha_s, H_s) \\
s_i &\sim H_b
\end{aligned} \tag{4.10}$$

where, $m_{i+1}|m_i$ denotes the conditional probability distribution over adjacent segments. H_b is the base distribution of the bigram model that is another Dirichlet process with a base distribution H_s (i.e. the morpheme length is used for the base distribution again) that generates each unigram segment in the model.

Once the probability distribution $p(m_{i+1}|m_i)$ is drawn from a Dirichlet process, the adjacent morphemes can be generated by a Markov chain. Here we do not want to estimate H_b and we integrate it out as follows:

$$\begin{aligned}
&p((s_1, s_2), (s_2, s_3) \dots, (s_{M-1}, s_M)) \\
&= \int p(H_b) \prod_{i=1}^M p((s_{i-1}, s_i) | H_b) dH_b
\end{aligned} \tag{4.11}$$

where M denotes the total number of bigram tokens. Therefore joint probability distribution as follows:

$$\begin{aligned}
&p(s_1, s_2, \dots, s_M) \\
&= p(s_1) p(s_2 | s_1) p(s_3 | s_2), \\
&\dots, p(s_n | s_{M-1}) p('0' | s_M)
\end{aligned} \tag{4.12}$$

where “0” is the end of the word sign inserted into the bigram and s_1 is the first segment of the word w that assumed as a stem. Where probability of a bigram $p(s_i, s_{i-1})$ drawn from two distinct DPs with a hierarchy.

If we call each bigram as $b = (s_i | s_{i-1})$:

$$p(w = \{s_1, s_2, \dots, s_M\}) = p(s_1) p(b_1) p(b_2), \dots p(b_M) \tag{4.13}$$

where M denotes the number of unique bigrams and $p(s_1)$ is drawn from H_s . The conditional probability of a bigram calculated according to the CRP, given previously generated segments $M = \{s_1, s_2, \dots, s_n\}$ as follows:

$$\begin{aligned}
&p((s_R | s_L)_{b_i} | B^{-b_i}, S^{-s_L}, S^{-s_R}, \alpha_b, H_b, \alpha_s, H_s) \\
&= \begin{cases} \frac{n_{b_i}^{B^{-b_i}}}{N_{s_L}^{S^{-s_L}} + \alpha_b} & \text{if } b_i \in B^{-b_i} \\ \frac{\alpha_b * p(s_R)}{N_{s_L}^{S^{-s_L}} + \alpha_b} & \text{otherwise} \end{cases}
\end{aligned} \tag{4.14}$$

where $n_{b_i}^{B-b_i}$ denotes the number of bigrams of type b_i when the new instance of the bigram b_i is excluded. Here B denotes the bigram set that involves all bigram tokens in the model. $N_{s_L}^{S-s_L}$ is the total number of bigram tokens in the model. s_L and s_R denote the left and right nodes of the bigram. Therefore, if the bigram b_i exists in the model, the probability of generating the same bigram again is proportional with the number of bigram tokens of the same type. If the bigram does not exist in the model, it is generated with the probability proportional to the number of right morpheme in the bigram:

$$p(s_R | S^{-s_R}, \alpha_s, H_s) = \begin{cases} \frac{n_{s_R}^{S-s_R}}{N^{S-s_R} + \alpha_s} \text{if } s_R \in S^{-s_R} \\ \frac{\alpha_s * H_s(s_R)}{N^{S-s_R} + \alpha_s} \text{else} \end{cases} \quad (4.15)$$

where $n_{s_R}^{S-s_R}$ is the number of segments of type s_R in S when the new segment s_R is excluded. N^{S-s_R} is the total number of segment tokens in S that excludes s_R . If the segment s_R exists in the model, it is generated again with a probability proportional to its frequency in the model. If it does not exist in the model, it is generated proportionally with the base distribution, therefore shorter morpheme lengths are favored.

The hierarchical model is useful for modeling dependencies between co-occurring segments. The co-occurrence of unseen segments are also within the scope of the hierarchical model. The prediction capability of the model comes from the hierarchical modeling of co-occurrences, which leads to a natural smoothing. For example, the segment bigram may not be seen in the corpus, however it is smoothed with one of the segments in the bigram which leads to a kind of natural interpolation.

4.5 Inference

We use Metropolis-Hastings algorithm to learn word segmentations in the given dataset. As presented in algorithm 2, Words are randomly split initially: We pick a word from the dataset in each iteration and randomly split that word. We calculate the new joint probability P_{new} of the model and compare it with the old joint probability of the model P_{old} . We either accept or reject the new sample according to the proportion of two probabilities:

$$\frac{P_{new}}{P_{old}} \quad (4.16)$$

If $\frac{P_{new}}{P_{old}} > 1$, the new sample is accepted. Otherwise, the new sample is still accepted with probability $\frac{P_{new}}{P_{old}}$.

Algorithm 2 The Inference Algorithm

```
1: input: data  $D = \{w_1 = s_1 + m_1, \dots, w_n = s_n + m_n\}$ , initial segment sequence  $S$ 
2: initialize:  $i \leftarrow 1, w \leftarrow w_i = s_i + m_i$ 
3: for all  $w$  in  $D$  do:
4:   Get new random segments of  $S$  as  $S_{new}$ 
5:   Delete the segments  $S_{old}$ 
6:    $p_{old}(D|S_{old}) \leftarrow p(D|S_{old})$ 
7:    $p_{new}(D|S_{new}) \leftarrow p(D|S_{new})$ 
8:   if  $p_{new} > p_{old}$  then
9:     Accept new segments of  $w_i$ 
10:     $S_{old} \leftarrow S_{new}$ 
11:   else
12:      $random \sim Normal(0, 1)$ 
13:     if  $random < (p_{new}/p_{old})$  then
14:       Accept new segments of  $w_i$ 
15:        $S_{old} \leftarrow S_{new}$ 
16:     else
17:       Reject the new segments
18:       Insert old segments  $S_{old}$ 
19: output: Optimal segments of input words
```

4.6 Results and Evaluation

For both models, two sets of experiments were implemented, one with a filtering algorithm and the other without a filtering algorithm. The first set of experiments, designed to test unsupervised unigram and HDP bigram models. The second set of experiments, designed to observe the effect of filtering algorithm as semi-supervision on unigram and HDP bigram models. In both experiments, words were assumed to be made of stems and suffixes where prefixes excluded. The test set chosen, was the Morpho Challenge 2010 Turkish dataset¹ wordlist, which consists of 617,298 words combined with word frequencies. Frequencies were not included with respect to the non-parametric nature of the model. Numeric results; precision, recall and f-measure provided in the tables are obtained using MC² evaluation metric which is suggested by morphochallenge 2010. In order to calculate the precision, two words that share a common segment are selected randomly from the results and checked whether they really share a common segment according to the gold segmentations. One point is given for each correct segment. Recall is estimated similarly by selecting two words that share a common segment in the gold segmentations. The F-measure is the harmonic mean of Precision and Recall:

$$F - measure = \frac{1}{\frac{1}{Precision} + \frac{1}{Recall}} \quad (4.17)$$

Additionally, EMMA metric suggested by Spiegler and Monson (2010) could be used as evaluation metric. For each experiment set, the sparsity of distributions were defined by constants α and γ . We manipulated parameters in order to fit our model into data.

¹ <http://research.ics.aalto.fi/events/morphochallenge2010/data/wordlist.tur>

² <http://research.ics.aalto.fi/events/morphochallenge2010/evaluation.shtml>

4.6.1 Experiments With Unsupervised Models

The results from the unigram unsupervised model are presented in Table 4.1. The model archived the f-measure value of 30.64 with $\alpha = 0.5$ and $\Gamma = 0.5$ values. There is a significant gap between precision and recall. The low recall reveals that the amount of unpredicted morphemes are high which, may due to undersegmentation.

Table 4.1: Results from unsupervised unigram model

Parameters α and Γ	Precision(%)	Recall(%)	F-measure(%)
0.01	77.09%	19.12%	30.64%
0.05	77.20%	19.87%	30.08%
0.1	94.71%	17.28%	29.23%
0.5	92.47%	18.02%	30.17%

Bigram model made a major improvement on results, the smoothing capability of the model made improvement on recall. The highest obtained F-measure by bi-gram HDP model is 38.83% as presented in Table 4.2. The main reason of improvement over results is that the bigram model is sensitive to co-occurrences while HDP provides room for unseen segments.

Table 4.2: Results from unsupervised bigram HDP model

Parameters α and Γ	Precision(%)	Recall(%)	F-measure(%)
0.1	42.31%	34.03%	37.72%
0.3	50.36%	31.60%	38.83%
0.5	45.09%	33.32%	38.32%
0.8	27.37%	48.17%	34.90%

Adding co-occurrences morphemes to the model, made a significant improvement over both F-measure and the gap between precision and recall. This advantage of HDP bi-gram model over unigram model may lead to two conclusions: Firstly, from a linguistic perspective, syntactic information about the morphemes has an important impact on segmentation that can not be ignored by independent morphemes assumption. Providing room for co-occurrences of the morphemes into the unsupervised model, provides a language specific information that improves number of valid segments. Secondly, the smoothing made by hierarchical model, significantly improved the results from DP. For languages with agglutinative structure, it is important to include smoothing into the model. Thus, the hierarchical DPs are better models for segmenting sparsely distributed data.

4.6.2 Experiments With Semi-supervised Models

The filtering algorithm, considerably improved overall performance of the model. Except the result of the 0.01 parameter in table 4.3, the improvements are quite reasonable; the recall value of % 24.74 may be explained as an outlier.

Semi-supervision also made a significant improvement over F-measure values, and the

Table 4.3: Results from semi-supervised unigram model

Parameters α and Γ	Precision(%)	Recall(%)	F-measure(%)
0.01	93.65%	14.25%	24.74%
0.05	72.83%	20.71%	32.25%
0.1	69.98%	26.40%	38.33%
0.3	87.10%	21.52%	34.52%

gap between precision and recall closed. The highest F-measure improved from % 38.83 to % 43.22 with a % 11.31 gap between precision and recall.

Table 4.4: Results from semi-supervised bigram HDP model

Parameters α and Γ	Precision(%)	Recall(%)	F-measure(%)
0.1	43.68%	41.41%	42.51%
0.3	46.92%	40.05%	43.21%
0.5	49.21%	38.52%	43.22%
0.8	49.46%	34.00%	40.30%

Clustering of morphemes into the allomorphs made a major improvement on overall results. With the filtering algorithm, number of possible suffix forms reduced to possible allomorphs. The number of tables are also reduced with respect to the rich-get-richer behaviour of DP. Therefore, decision making capability of the algorithm increased over each segment sequences which, reduced the sparsity. As both Figure 4.4 and Figure 4.4reveals, supervision consistently increases f-measure.

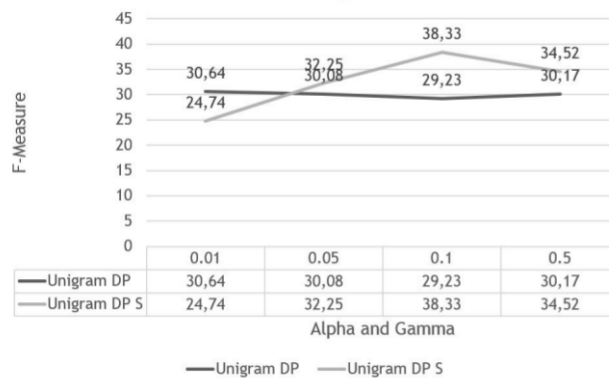


Figure 4.4: Comparison of Results From Unigram Models

Kohonen et al. (2008) presented an extension to Morfessor baseline (Creutz and Lagus, 2002) for unsupervised induction of allomorphy namely, allomorfessor. Their system was a morphological segmentation model that identifies potential base forms for stems, but not suffixes. The allomorphy of stems are aimed to discover by a MAP model for consonant mutations. Test set was Morpho Challenge 2008 data set³, the results were pointing a high undersegmentation with %11.53 F-measure for Turkish. Their model

³ <http://research.ics.aalto.fi/events/morphochallenge2008/>

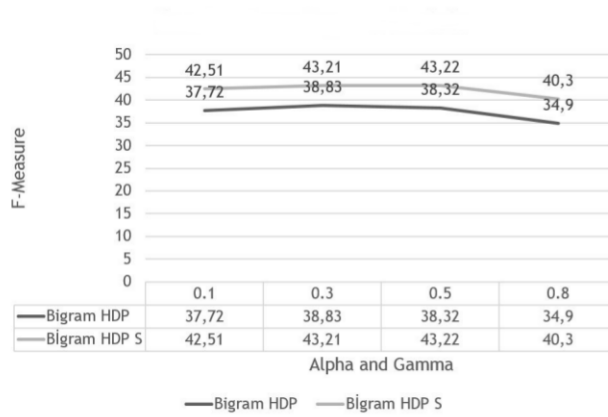


Figure 4.5: Comparison of Results From Bigram Models

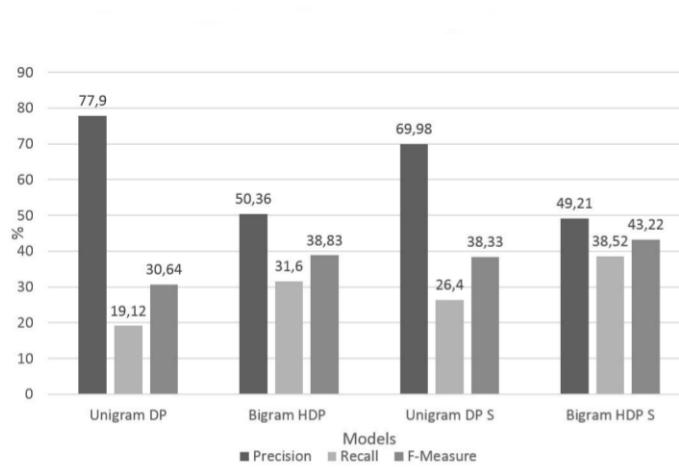


Figure 4.6: Comparison of Results With The Highest F-measure

suffered from lacking context information as our unigram model suffers. The semi-supervised HDP bigram model resolves that problem by considering adjacency and extracting global information about segmentation. Additionally, allomorph filtering provides a tuning over parameters which, reduce uncertainty.

Virpioja et al. 2009, presented another extension to Morfessor baseline (*ibid*) named Allomorfessor baseline which, aim to obtain better results than Allomorfessor (Kohonen et al., 2008) by creating a morpheme-level model that is able to manipulate surface forms of the morphemes, with *mutations*. Their model resulted an F-measure of %31.82 over Turkish dataset⁴ with a huge gap between precision and recall. While their model results %62.31 F-measure over English dataset⁵, the results for Turkish are quite low compared to our results from unigram and HDP bigram unsupervised models. This may lead to a conclusion that the allomorphy may not be able to modeled by consonant mutations, it needs global information about morphological forms to model such phenomena. The Dirichlet process is a suitable model compared to mutation-based form manipulation systems.

⁴ <http://research.ics.aalto.fi/events/morphochallenge2009/>

⁵ <http://research.ics.aalto.fi/events/morphochallenge2009/>

4.7 Comparison With Other Systems

We compare our results with other unsupervised systems participated in Morpho Challenge 2010, as our dataset and evaluation algorithm are taken from Morpho Challenge 2010. The comparison of our semi-supervised model made with the unsupervised algorithms with supervised parameter tuning of Morpho Challenge 2010. Because of the semi-supervised models of Morpho Challenge 2010 are using gold standard segmentations for supervision.

Table 4.5: Comparison of our semi-supervised model with other algorithms with supervised parameter tuning participated in Morpho Challenge 2010 for Turkish

System	Precision(%)	Recall(%)	F-measure(%)
Promodes Spiegler et al. (2010)	46.59%	51.67%	49.00%
Promodes-E Spiegler et al. (2010)	40.75%	52.39%	45.84%
Morfessor U+W Kohonen et al. (2010)	40.71%	46.76%	43.52%
Bigram HDP with Filtering	49.21%	38.52%	43.22%
Promodes-H Spiegler et al. (2010)	47.88%	39.37%	43.21%

Table 4.6: Comparison of our unsupervised model with other unsupervised systems in Morpho Challenge 2010 for Turkish

System	Precision(%)	Recall(%)	F-measure(%)
Morfessor CatMAP Creutz and Lagus (2005)	79.38%	31.88%	45.49%
Aggressive Compounding Lignos (2010)	55.51%	34.36%	42.45%
Bigram HDP	50.36%	31.60%	38.83%
Iterative Compounding Lignos (2010)	68.69%	21.44%	32.68%
MorphAcq Nicolas et al. (2010)	79.02%	19.78%	19.78%
Morfessor Baseline Creutz and Lagus (2002)	89.68%	17.78%	29.67%
Base Inference Lignos (2010)	72.81%	16.11%	26.38%

Tables 4.5 and 4.6 presents the official results of the Morpho Challenge 2010 (Kurimo et al., 2010). The most accurate unsupervised segmentation system Morfessor CatMAP, is based on a MAP model with involve of the form and the meaning of morphs where the meaning consists of a set of features; frequency of the morph, perplexity⁶ and the length in letters of the morph. The involve of meaning do not impose any semantic information, but it is an attempt to infer as much as knowledge from the context. Bigram HDP model also revealed that the context sensitivity is important in segmentation models.

The Promodes algorithm family is based on a probabilistic generative model. The parameters, letter transition probability and probability distribution over non-/boundaries are estimated by computing MLE from the goldsegment training set which, used for to finding best segmentation of the word. The Promodes, applies the information of training set to a larger test set without any linguistic assumption i.e. stem and affix. The accuracy of Promodes revealed that the transitional probabilities between letters are also important in morphological segmentation task.

⁶ As “distilled” properties of the context the morph occurs in, its intra-word right and left perplexity are considered.

CHAPTER 5

CONCLUSION AND FUTURE WORK

Morphology is a significant subdiscipline of linguistics, an interface between phonology, syntax and semantics. In agglutinating languages, morphology plays a key role on understanding language acquisition and word internal structures. To be more specific, for an infant to learn Turkish, LA is a task of acquisition of morphemes in which, word internal structures are acquired with respect to morphosyntactic forms and their semantic properties.

Our form driven approach claims nothing about semantics, symbols and representational system of mind. In natural languages, phonological form contains the information about the syntactic properties of source language. The unsupervised models of morphological segmentation are to extract information from the phonological forms. The form-driven models suffer from the lack of semantic information, thus, it is quite expected from them to dismiss linguistic phenomena such as dependency structures. Even if shortcoming of the form-driven approaches is unavoidable, it is important to understand how much of the information could be successfully extracted from the syntactic forms. Thus, this study based on a phonological form-driven non-parametric model for morphology learning. The research questions presented in section 1.1 are concluded accordingly:

1. While usefulness of non-parametric Bayesian models in computational models is undoubtedly important, when it comes to modeling of learning, they are not explanatory but robust frameworks for detecting patterns in the data. In case of a form-driven model, the form itself is not enough to have a segmentation model that widely covers morphology. Accommodating the co-occurrences of morphosyntactic forms i.e. bigrams into a form-driven model, improves the coverage and the robustness.
2. The supervision of non-parametric Bayesian models is promising as our minimal supervision achieved better results. Incorporating orthographic rules as prior information into the form-driven model, resulted in better segmentations. Therefore, the allomorphy is a useful prior for morphological segmentation task.

Our study made two major contributions to the morphological segmentation research; firstly, we revealed that it is important to include intra-word dependencies to the non-parametric Bayesian model. Secondly, using allomorphy for tuning the parameters of a non-parametric Bayesian model, results with a more successful clustering of morphemes.

As our study reveals that, the phonological forms explain just little amount of learning unless they are combined with logical forms. Unlike formal languages, natural languages are much more complex to process with phonological forms. Unsupervised and semi-supervised models of language learning are not explanatory yet. According to LOTH, they would never become a cognitive model neither, but are useful at reducing innate assumptions.

5.0.1 Future Work

In order to carry this research further, some modifications to could be implemented. As well-known Zipfian distribution provides empirical information about the morphology Chan (2008), adding the Mandelbrot's Zipfian formula definition to our non-parametric Bayesian model as a base distribution, could provide information about relationship between morpheme occurrences and probabilities Creutz (2003). The word frequencies of our dataset are not included yet into our segmentation models, they can be included as a strength parameter for each segment of the word. As Creutz Creutz and Lagus (2005) shows that the maximizing information inferred from the context, improves the segmentation performance we can place further assumptions into our model such as derivative and inflective forms. A distance dependent CRP Blei and Frazier (2011) that groups the similar data with a distance function, could be defined in order to get better clusters of such categories.

As Çakıcı et al. (2016) shows that the combinatory categorial grammars¹ (CCG) and radical lexicalization are explanatory approaches to language learning. The universal rules of CCG i.e. *application*, *type-raising* could be useful in deducing the grammar from the phonological and the logical form. Such system also have degrees of freedom for unseen forms with categorial projection. Thus, the actual HDP model could be modified to induce CCG from morphology as Bisk and Hockenmeier 2013 shows that such models can compete with other grammar induction systems.

¹ Steedman (2000), Steedman (2012), Bozşahin (2012)

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